Draft Specification Postamp / Comparator (Discriminator)

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Version 2.3

Table of Contents

1.0 General Information	4
1.1 Overview	4
1.11 Standard Bus Systems Used	4
1.12 Number of Channels	4
1.2 Application	4
1.3 Packaging	4
1.31 Physical Size	4
1.32 Pinouts	4
1.33 Front Panel Displays	5
1.4 Power Requirements	5
1.41 Control and Monitoring Requirements	5
1.5 Cooling Requirements	5
2.0 Theory of Operation and Operating Modes	6
2.1 Basic Operation	6

	2.11	Inputs	6
	2.12	IC-01 - Discriminator / Latch	6
	2.13	IC-02 - Logic & Latch Pulse Fanout	7
	2.14	1C-03 - DAC / ADC	7
	2.15	IC-04 - Trigger Sums	7
	2.16	Test Circuit	7
	2.17	FASTBUS Interface	8
2.2	Addres	ssing Modes	15
	2.21	Error Responses	15
	2.22	Diagnostic Software	
3.0	Input /	Output Specifications	
4.0	System	n Software Description (FASTBUS Comm	ands)
5.0	Diagno	ostics	
5	.1 Ha	rdware	
	5.11	Test Setup Description	

5.12 Operating Instructions

5.2 Software

6.0 Appendices

16

1.0 <u>General Information</u>

1.1 <u>Overview</u>

The purpose of the <u>Postamp / Comparator</u> (P / C) module is to compare the voltage amplitude of the pulses, at the input of this module, to a reference voltage (the threshold voltage) and to latch a logic level output for each pulse greater than that programmable reference voltage. The latching of the logic levels is synchronized with a 53 MHz clock provided by a <u>sequencer</u> module. Differential input signals are received from <u>Silicon Strip Detector (SSD) amplifiers</u> through four 64-conductor ribbon cable connectors mounted on the front portion of the P/C module. ECL level output signals are sent, via a custom auxiliary backplane, to a <u>delay / encoder</u> module located in an adjacent slot in the FASTBUS crate. Eight fast analog sums and eight analog encoded digital sums, intended for use by the prompt trigger logic, are constructed and output through FASTBUS auxiliary cards. These signals also provide a means of debugging a PC module with an oscilloscope without the need of an extender card.

1.11 Standard Bus System Used

The Postamp/Comparator module is a FASTBUS slave module designed to be used together with a delay / encoder module in a FASTBUS crate equipped with an SSD Readout auxiliary backplane.

1.12 Number of Channels

The Postamp/Comparator module is a 128 channel module.

1.2 Application

This module was designed for use in the fast <u>Silicon Strip Detector</u> (SSD) readout system developed at FNAL for use by E-771 and E-789. It is directly usable only in the context of this readout system.

1.3 Packaging

This board is a standard single width FASTBUS module (see ANSI / IEEE Std 960-1986).

1.31 Physical Size

The maximum board dimensions are 14.437 inches high by 15.878 inches deep. The board thickness is between 0.086 inches and 0.100 inches.

1.32 Pinout

See Appendix 6.

1.33 Front Panel Displays

The following front panel display LED's are implemented:

NAME	COLOR	ENERGIZED MEANING
Mode	Red	module is in the INITIALIZE (TEST) mode.
Mode	Green	module is in the RUN mode.
Clock	Yellow	CLOCK 1 (53 Mhz) is present.
Select	Yellow	Module is being accessed via FASTBUS
Temp.	Red	Module temperature is > 50 degrees C.
Clock Select	Yellow Yellow	CLOCK 1 (53 Mhz) is present. Module is being accessed via FASTBUS

1.4 Power Requirements

The Postamp/Comparator module uses the following voltages which are distributed on the FASTBUS backplane:

+5.0 V	6.6 Amps
-5.2 V	7.9 Amps
-2.0 V	0.16 Amps

Five additional voltages are derived from these and used by the ASIC's. They are:

+3.5 V	4.0 Amps
-1.0 V	0.16 Amps
-3.5 V	4.4 Amps

1.41 Control and Monitoring Requirements

All power supply voltages distributed on the FASTBUS backplane will be monitored by a CAMAC based system. This system will be read out into EPICURE.

1.5 Cooling Requirements

The total power dissipated on the board will not exceed 75 watts.



2.0 Theory of Operation and Operating Modes

2.1 Basic Operation

2.11 <u>Inputs</u>

128, SSD preamplifier signals are received at the Postamp/Comparator module via four, 64-conductor ribbon cables. The input signal order does not correspond to the order of the silicon strips in the detector for reasons having to do with signal density on both the detector itself and the amplifier cards connected to the detector. The input signal traces on the Postamp/Comparator module are routed to restore the monotonic strip order of the detector. These differential signals are coupled through $.1\mu F$ capacitors to the inputs of the IC-01 ASIC's , and both sides terminated through $50~\Omega$ to ground. These termination components are housed in a custom 10-lead sip each of which will terminate two channels (4 wires) of the 128 channels; thus 64 sips per module.

2.12 IC-01: SSD Two Channel Sum, Discriminator and Latch

IC-01 is a bipolar ASIC made using a Tektronix Quickchip 2K-130 linear array. It contains two linear summing amplifiers, four time-over-threshold comparators (with variable threshold setting capability and hysteresis), and four latches (see Appendicies). Each IC-01 (except for the units with the lowest and highest numbered channels on the board) receives signals from three consecutive silicon strips. The first and third signals are also input to neighboring IC-01 chips. Two linear sums are made; the first by adding the first and second inputs, and the second by adding the second and third inputs. The output of each of the two linear sums is input to a comparator. The output of the second sum is also sent to IC-04. The second and third inputs are connected to the remaining two comparators. The result is two pairs of comparators, one pair discriminating individual strip signals (inputs two and three), and the other pair discriminating the two sum outputs. Each discriminator has a separate threshold setting input. The output of each of the four comparators is sent directly to a transparent latch (one per comparator) which is controlled by a differential, 2.5 ns wide LATCH input signal. This LATCH signal, common to all four latches, controls the function of the latches, which can be thought of as digital sample-and-holds. When the LATCH control lines are in the "transparent" state, the LATCH output follows the comparator output. When the LATCH is in the "latched" state, the output of the LATCH remains unchanged. In normal operation, an ASIC (IC-02) located within three inches of each IC-01 provides this 2.5 ns wide pulse. This LATCH pulse is synchronized to the 53 MHz CLK1 signal received from a sequencer. This pulse switches the LATCH input from "latched" mode to "transparent" mode for a time equal to the width of the pulse, and then returns it to the "latched" mode. The result is that the state of the comparator is latched and held for one RF cycle less the width of the LATCH pulse. Two more control signals, called INDIVIDUAL CHANNEL FORCE ZERO and SUMMED CHANNEL FORCE ZERO, also effect the operation of the latches. INDIVIDUAL CHANNEL FORCE ZERO is

connected to the two individual strip latches and SUMMED CHANNEL FORCE ZERO is connected to the sum latches. When FORCE ZERO is HI, the effected latches are forced to logical zero. This function is used to insure that no signal is received from an IC-01 chip while the discriminator board is in the INITIALIZE / TEST mode (see below). It also makes it possible to disable either bank of comparators while leaving the other bank operational.

2.13 IC-02 - 3-Channel Logic, Quad Analog Sum & Latch Driver

The IC-01 latched outputs are input to two other bipolar ASIC's (IC-02 and IC-04) made using Tektronix Quickchip 2K-130 linear arrays (see figure 2). The combination of these two chips accept inputs from four IC-01's (8 SSD channels), and produces eight ECL outputs which are sent, via the auxiliary backplane, to the delay / encoder board in the adjacent slot to the right (viewed from the front of the FASTBUS crate). The logic producing these eight ECL signals performs in the following way: any given output channel N is set HIGH if the corresponding single strip (N) latch is set, or if one of the summed-channel latches including strip N is set, but neither of the individual channel latches for the two channels contributing to the sum are set. These signals are OR'ed with test inputs which sit at logical low levels while the module is in the RUN mode. Test signals are sent to these test inputs in the TEST mode during which time the latch outputs are forced to a logical zero.

IC-04 is also used to produce a signal known as NHIT or DIGITAL SUM which consists of a current, the magnitude of which is proportional (100 uA / strip hit) to the number of hit strips in the group of eight. The NHIT inputs are constructed by both IC-02 and IC-04, forming a logical OR of a single strip signal and one of the summed channel signals which has that strip as one of it's inputs. The result is that the output of NHIT will register a ONE if a hit is shared by two adjacent strips even though two bits (for two adjacent strips) are set in the delay / encoder.

IC-02, similar to IC-04, produces an ANALOG SUM of the same eight strips used in producing NHit. The difference being that this output current is truely a linear sum of the eight individual strip signals. IC-02 also has the circuitry to accept a narrow pulse (2.5 ns wide) and fan out a differential version of this pulse to the LATCH inputs of four IC-01 Sum, Discriminator and Latch chips.

2.14 <u>IC-03 - DAC / ADC</u>

Voltage levels are provided for the threshold voltage (Vth) inputs of the IC-01 Sum, Discriminator and Latch chips by a CMOS ASIC produced by United Silicon Structures. This chip contains four 8 bit D/A converters and one 8 bit A/D converter. This A/D converter requires an on board 100 kHz clock which can be turned on or off via CSR0. Up to 64 DAC chips may be mounted, providing individual control of the 256 discriminators on a Postamp/Comparator module. The DAC chips are loaded under FASTBUS control and the analog outputs (Vth) are measured by the integral A/D and read back via FASTBUS. The IC-03 chips

share 8 data lines and 4 control lines. Each chip has a separate select line. The DAC outputs may be jumpered together to allow the use of as few as one DAC chip on the Postamp/Comparator module. The output range is from 0 V to the reference 2.55 V. The output impedance of these DACs varies between 10 and 30 Ω . Each chip requires power supply voltages of -1, +5 and a reference voltage of +2.55.

2.15 IC-04 - SSD 5-Channel Logic and Octal NHit

See section 2.13

2.16 Test Circuit

A presetable 8 bit counter is included on the Postamp/Comparator module to provide a means of sending test data to the <u>delay / encoder</u> module associated with the Postamp/Comparator module. This counter is controlled through FASTBUS. The counter's outputs are reset (forced to zero) when the discrimintor board is in the RUN mode. When the board is in the INITIALIZE (TEST) mode, the counter may be set in the count or hold mode. In the hold mode, the counter output pattern can be altered by presetting the counter via FASTBUS. In the count mode, the counter is incremented by the CLK1 signal. The connection of the test counter to IC-02 and IC-04 is illustrated in figure 1. This means that 256 unique patterns may be sent to the <u>delay / encoder</u> board. The test pattern may be static i.e., altered by presetting the counter via FASTBUS or may change every 18.9 ns by being incremented by CLK 1.

2.17 **FASTBUS** Interface

The discriminator is a FASTBUS slave. It responds to geographic addressing in control space only. It allows both single and block transfers and contains the following registers:

CSRO This is the main control and status register. It is a selective set and reset register with the following bit assignments:

BIT 02 RUN / HALT	Writing a "1" to this bit puts the module in the RUN mode. A "0" must be simultaneously written to BIT 18. This bit is cleared by writing a "1" to BIT 18 (HALT).
BIT 06 EN_IC	Writing a "1" to this bit ENABLES the individual strip latches. Has the opposite effect as that of BIT 06.

BIT 07 -- EN_SC Writing this bit ENABLES the summed channel latches = clears bit 07 (FORCE ZERO=OFF).

BIT 08 CCLK_EN	When HALTED, setting this bit enables the clock to the 8-bit test counter. The clock is disabled while the module is in the RUN mode.
BIT 09 - CLK1_ON	This bit will READ ONE whenever CLK1 (53 MHz) is present.
BIT 10 ADCCLK_EN	Writing a "1" to this bit ENABLES the 100 kHz clock which is used by the ADC portion of the DAC / ADC units.
BIT 18 HALT	Writing a "1" to this bit places the module in the INITIALIZE / TEST mode (In this mode all latch outputs are FORCED to ZERO). A "0" must be simultaneously written to BIT 02.
BIT 22 FZ_IC	Writing a "1" to this bit FORCEs the individual channel latch outputs to ZERO. A "0" must be simultaneously written to BIT 22. This bit is cleared by writing a "1" to bit 22. This bit will READ ONE if the individual strip latches are FORCED to ZERO.
BIT 23 FZ_SC	Writing a "1" to this bit FORCEs the summed Channel latch outputs to ZERO. A "0" must be simultaneously written to BIT 23. This bit is cleared by writing a "1" to bit 23. This bit will READ ONE if the summed channel latches are FORCED to ZERO.
BIT 24 CCLK_DIS	Writing to this bit disables the clock to the 8-bit test counter.
BIT 20-31 ID	The device ID is read back on these bits.
BIT 26 ADCCLK_DIS	Disables the 100 kHz clock enabled by bit 10

Preamp/Comparator (Discriminator) Module **BIT SET MEANING READBACK MEANING** 28 100 kHz CLOCK DISABLE* MODULE ID TEST COUNTER CLK DIS* 24 SUM CHANNEL FORCE ZERO* INDIVIDUAL CHANNEL FORCE ZERO* 20 MODE HALT* 16 12 100 kHz CLOCK ENABLE* 100 kHz CLOCK EN/DIS CLOCK 1 PRESENT/ABSENT TEST COUNTER CLK EN* 80 CLOCK 1 **EN/DIS** SUM CHANNEL ENABLE* SUM CHANNEL EN/DIS INDIVIDUAL CHANNEL ENABLE* INDIVIDUAL CHANNEL EN/DIS 04 MODE RUN* MODE RUN/HALT 00 ERROR FLAG

CSRO

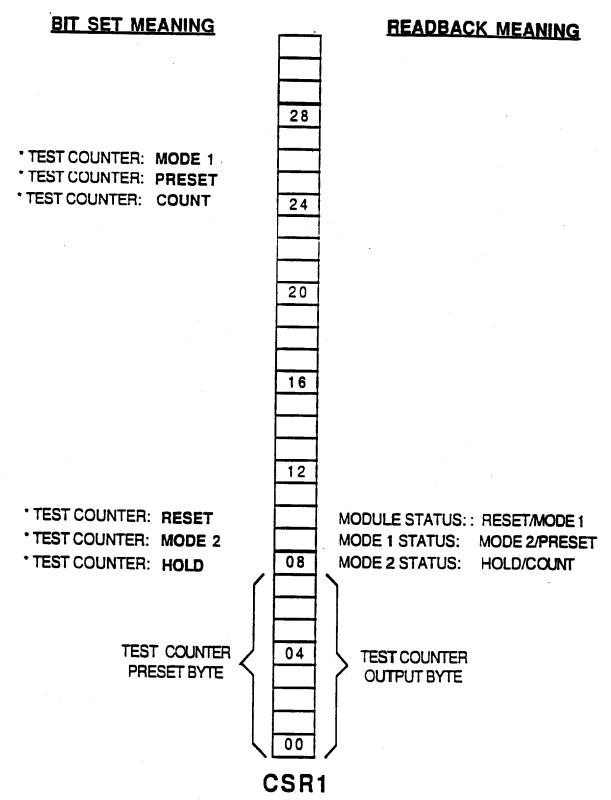
* The corresponding bit displaced 16 bits away must have a zero written simultaneously.

CSR1 This register is used to load and read the 8-bit test counter.

The counter is disabled when the module is in the RUN mode.

BIT 00-07 -- DATA Data to be loaded to / read back from the 8-bit test counter.

Preamp/Comparator (Discriminator) Module TEST COUNTER CONTROL AND STATUS



The corresponding bit displaced 16 bits away must have a zero written simultaneously.

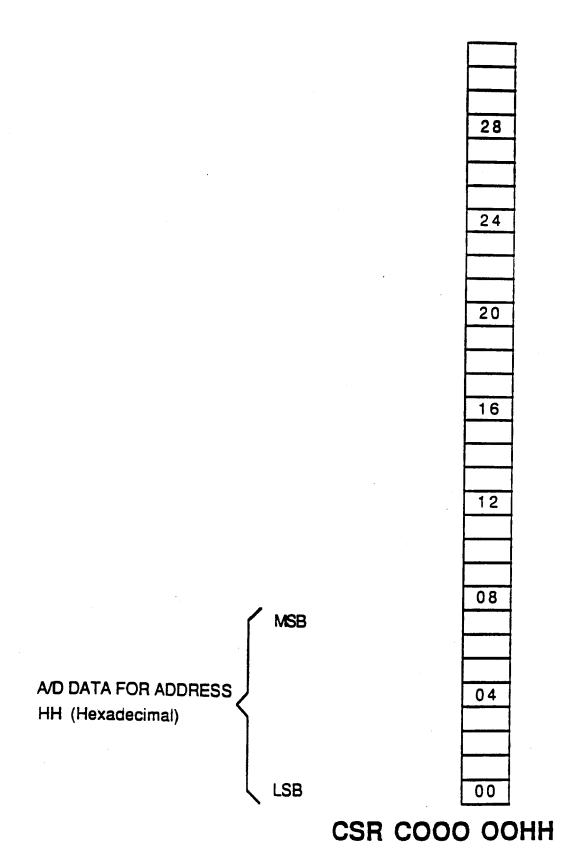
CSR C000__0000 - C000__00FF

These registers are used to load and read the threshold DAC's. They can be written only when the module is HALTed (in the INITIALIZE/TEST mode). The module returns an SS=6 if a write is attempted when in the RUN mode. This address range is programmable to match the number of DAC's installed on the board.

BIT 00-07 -- DATA

Data to be loaded to / read back from DAC's.

Preamp/Comparator (Discriminator) Module



2.2 Addressing Modes

2.21 <u>Error Responses</u>

The module asserts a FASTBUS error (SS=6) if an attempt is made to write to a threshold DAC while the board is in the RUN mode.2.2 Addressing Modes 2.3 Hardware Jumpers and Switches

2.31 DAC / ADC Jumpers

As was stated in section 2.14, the DAC outputs can be jumpered to allow a given output to be connected to one or more of any of the 256 discriminator threshold inputs.

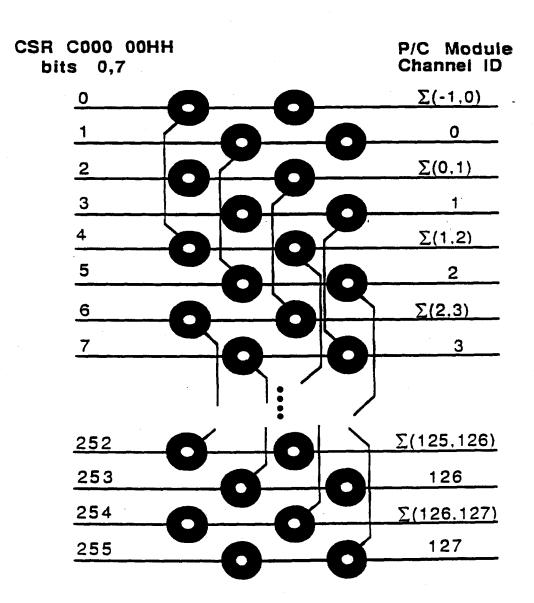
CSR C000 00HI bits 0,7	Н		P/C Module Channel ID
0	0_		Σ(-1,0)
1			<u> 0 ·</u>
2			Σ(0.1)
3			. 1
4			<u>Σ(1,2)</u>
5			2
6			$\Sigma(2,3)$
7			3
252	^		Σ(125,12 6)
253		;	126
254			Σ(126,127)
255			127

The above illustration is an abbreviated pattern of that which exists on the P/C Module. The lines on the left are connected to the DAC / ADC outputs and the lines on the right are connected to the threshold setting inputs.

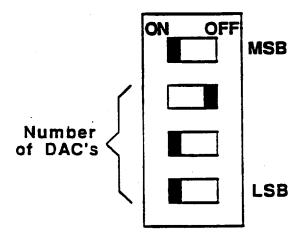
There are 256 DAC/ ADC's which are addressed via bits 0 through 7 of CSR C000 00HH. DAC address 00 (Hex), will always set the threshold voltage on the uppermost

trace which is the threshold for the discriminator connected to the output of the summed channel which takes the sum of channel -1 and channel 0 (Σ -1,0). Likewise DAC address 01 (Hex), will always set the threshold voltage on the trace immediately below the the uppermost trace which is the threshold for the discriminator connected directly to the channel 0 input. DAC address 02 (Hex), will always set the threshold voltage for the discriminator connected to the output of the summed channel which takes the sum of channel 0 and channel 1 (Σ 0,1). DAC address 03 (Hex), will always set the threshold voltage for the discriminator connected directly to the channel 1 input. This pattern continues for the 256 DAC /ADC's and the 256 discriminators.

It should be obvious that if all 256 DAC 's are employed, no jumpers are required. However, in the event that only 4 of the 256 DAC's are mounted on the P/C Module, the jumpers would probably be applied as illustrated below. In this case DAC 00 (hex) would drive every other sum channel. i.e., $\Sigma(-1,0)$, $\Sigma(1,2)$, $\Sigma(3,4)$, $\Sigma(5,6)$ etc. DAC 01 (hex) would drive the even individual channels; DAC 02 (hex) would drive sum channels $\Sigma(0,1)$, $\Sigma(2,3)$, $\Sigma(4,5)$, $\Sigma(6,7)$ etc., and DAC 03 (hex) would drive the odd, individual channels.



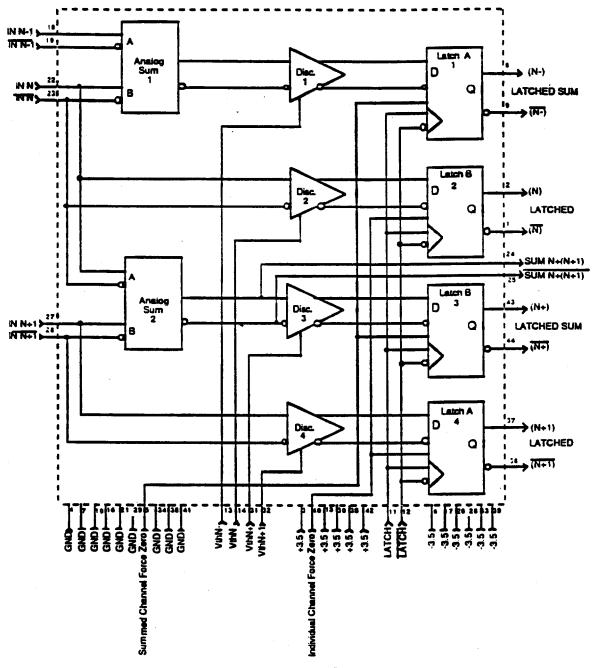
When less than 256 DAC's are utilized, the P/C module will be populated from the lowest address onward without skipping addresses. An on board,4 bit dip switch (illustrated below) utilizes 3 bits to indicate the number of DAC chips mounted. The choices are 0,4,8,16,32,64,128 or 256 which corresponds to 0,1,2,4,8,16,32 and 64 packages. It seems reasonable to assume that for four DAC's every fourth threshold lead would be connected togather and so on. However, any and all possibilities exist for connecting DAC outputs to threshold inputs and the methode used may be dictated by the detector geometry.



APPENDICIES

- 1. IC-01 2. IC-02 3. IC-03 4. IC-04

IC-01: SSD TWO CHANNEL SUM, DISCRIMINATOR AND LATCH Cavity Down



Part Number IC-01

NOTES:

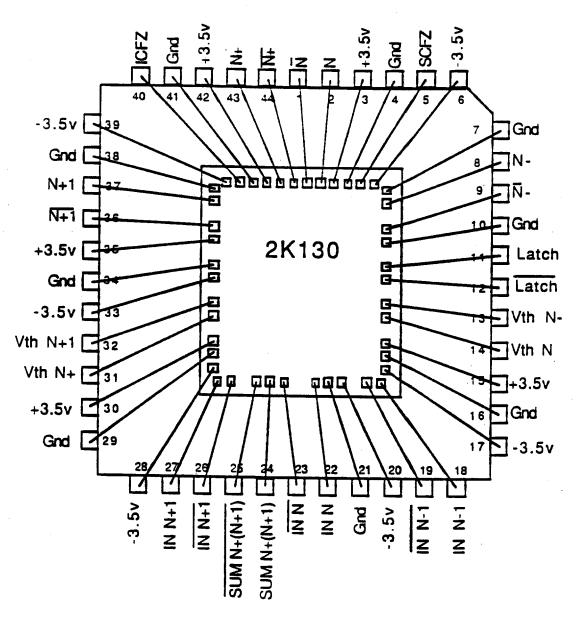
- All input and output signals are full differential except power, threshold (Vth#) and Force Zero.
- The discriminator compares the input amplitude with the threshold setting.
 If the input exceeds the setting, an output exists for the time over threshold.
- 3. The "LATCH" signal must be at least 1 Nanosecond wide.
- 4. Power dissipation is typically 406 mW; 504 mW max.
- Power supply currents: +0.5 V @typically 48 mA : 56 mA max.
 -3.5 V @typically 68 mA : 68 mA max.

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Revised 3-30-80
Merie Haldeman / Scott Holm

IC-01: SSD TWO CHANNEL SUM, DISCRIMINATOR and LATCH Cavity Down

Thermally Enhanced, 44 Lead Plastic Chip Carrier

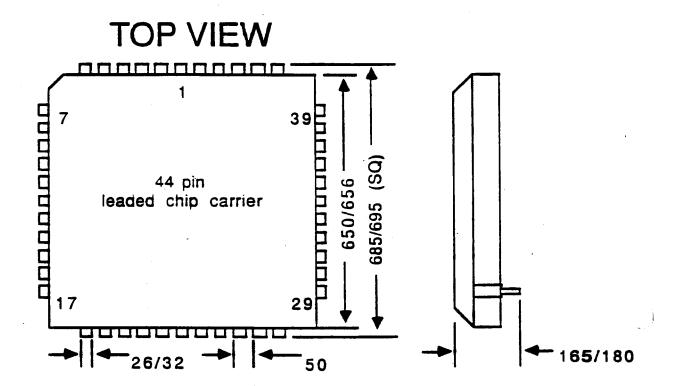
Part Number IC-01



BOTTOM VIEW

Created 8-28-89
Revised
Merie Haldeman / Scott Holm

IC-01: SSD TWO CHANNEL SUM, DISCRIMINATOR and LATCH Cavity Down



IC-01 Package Dimension Diagram Notes.

1. All dimensions are in mils. (Min/Max)

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Merle Haldeman / Scott Holm

IC-01 SSD TWO CHANNEL, DUAL SUM, QUAD DISCRIMINATOR AND QUAD LATCH

Overview

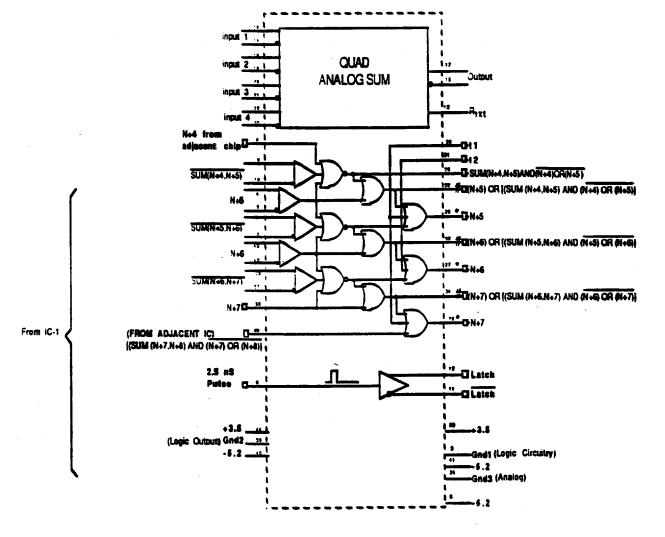
This IC is being designed for two experiments here at FERMILAB; E-771 and E-789. In E-771, a Silicon Strip Detector (SSD) produces signals which are amplified by preamplifiers and then transmitted over balanced,100 ohm impedance, transmission lines to the inputs of several of the IC-01 devices for further signal processing. These ICs will be mounted on a FASTBUS board approximately as illustrated in figure 1. These boards are then plugged into a FASTBUS Crates each of which is capable of housing 26 single width FASTBUS modules. This experiment has 24 planes with 688 strips per plane for a total of 16,512 strips to be read out.

Circuit Function

As can be seen in figure 2, IC-01 consists of two sum circuits, four discriminators and four latches. The four discriminators are identical. Each of the sum circuits has a differential voltage gain of approximately one. The purpose of this summing amplifier is to provide a signal voltage, when a charged particle passes between two strips, that has essentially the same amplitude as a that produced by the same particle passing solely through one strip. The output of these sum amplifiers drive the two discriminators which look for the shared signal condition.

The discrimiantors have a built in hysteresis which is equivalent to approximately 10 millivolts referred to the input. In this area of operation, the discriminator has sufficient positive feedback to provide infinite voltage gain. This gain only exists for an input variation of about ten millivolts. This feature is provided by current source "QCS3" and current switch transistors "Q300" and "Q301". There is a variable threshold input terminal which allows the input discriminate between input voltages from 5 to 50 millivolts for a dynamic range of 10 to 1. The threshold is controlled by the application of a DC voltage to terminal "VTHR".

iC-02: SSD 3-Channel Logic, Quad Analog Sum and Latch Driver



Notes:

- * Lines to Auxiliary Backplane
- # Lines to NHit
- ECL Levele

Power supply currents: +3.5 @ 21mA typ.: 27 mA max. -5.2 @ 62 mA typ.: 79 mA max.

			CUIPUTS			
N+5	SUM(N+5.N+6)	N+6	SUM(N+6,N+7)	N+7	N+6	N+6 OR
X	х	1	х	X	1	1
0	1	0	X	X	1	1
X	X	0	1	0	1	

All other input conditions produce zero outputs X = Don't Care

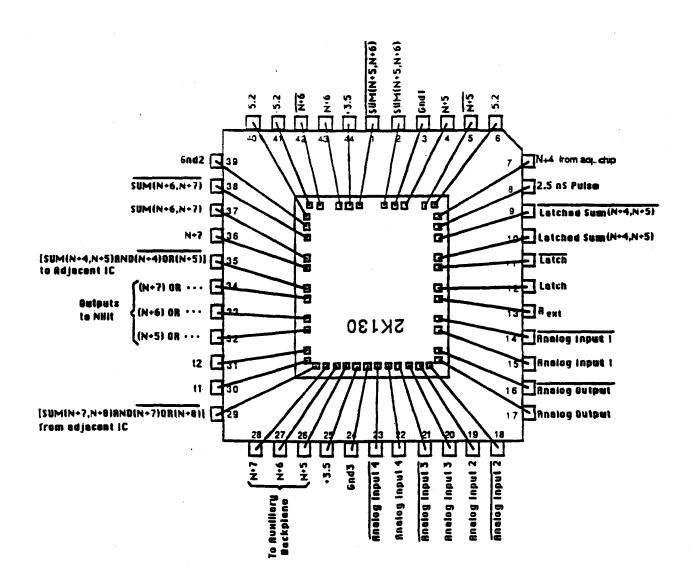
N+4	
N+5	
N+6-7-0-	
N-4	
CASE 1	CASE 2

- o Location of particle
- a Signals to NHit
- Signals to Auxiliary Backplane

IC-02: SSD 3-CHANNEL LOGIC, QUAD ANALOG SUM and LATCH DRIVER

Cavity Down
Thermally Enhanced, 44 Lead Plastic Chip Carrier

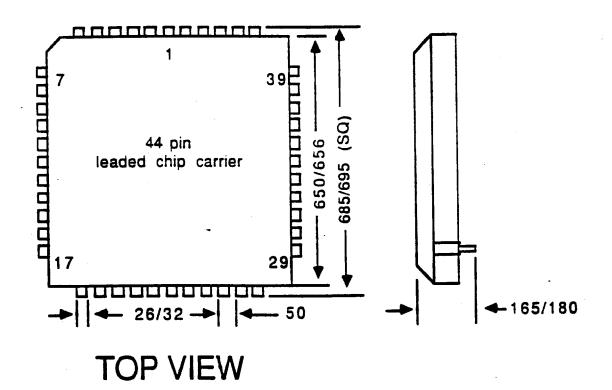
Part Number IC-02



BOTTOM VIEW

Created 8-28-89
Revised
Merie Haldeman / Bruce Merkei

IC-02: SSD 3- CHANNEL LOGIC, QUAD ANALOG SUM and LATCH DRIVER Cavity Down



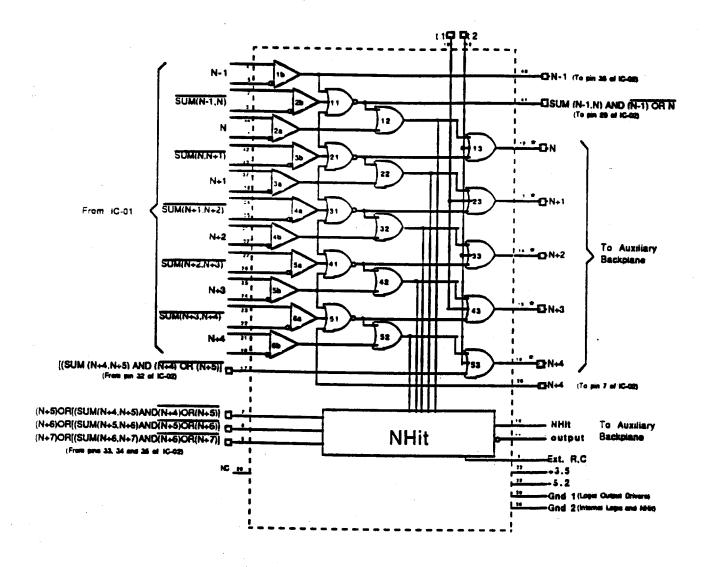
Part Number IC-02

IC-02 Package Dimension Diagram Notes.

1. All dimensions are in mils. (Min/Max)

Created 5-18-89 Revised 6-30-89 Merle Haldeman /Bruce Merkel

IC-04: SSD 5-Channel Logic and Octal NHit

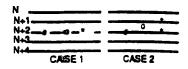


	INPUTS					DUTPUTS
N	SUM(N.N+1)	N+1	SUM(N+1.N+2)	N+2	N+1	N+1 OR [****
X	X	1	X	Х	1	1
0	1	0	Х	×	1	1
X	X	0	1	0	1	

All other input conditions produce zero outputs X = Don't Care

Power dissipation 350 mW Outputs unloaded.

Power dissipation 500 mW All outputs loaded with 100 chms to -2.0 Volts.

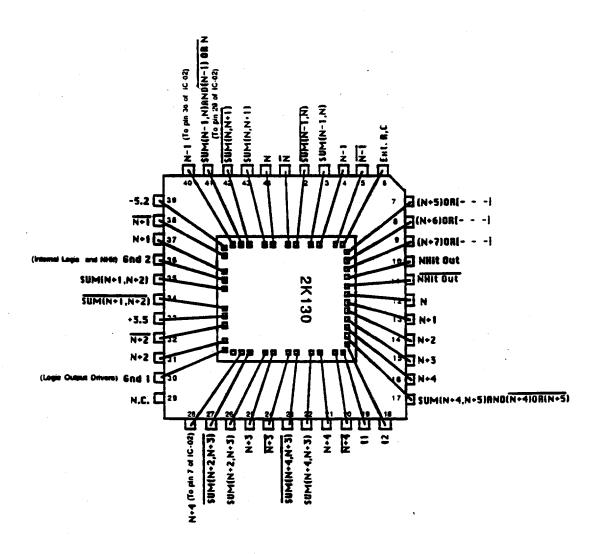


- o Location of particle in SSD
- # Signates to NHit
- * Signals to Auxiliary Backplane
- ☐ ECL Laveis

IC-04: SSD 5-CHANNEL LOGIC & OCTAL NHIT Cavity Down

Thermally Enhanced, 44 Lead Plastic Chip Carrier

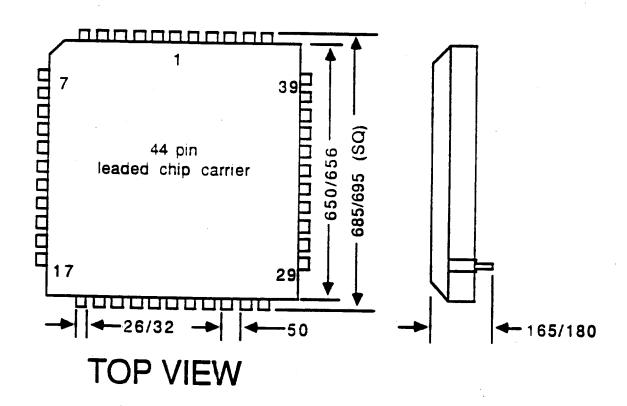
Part Number IC-04



BOTTOM VIEW

Created 8-29-89 Revised 8-29-89 Made Maideman / Jim H

IC-04: SSD 5-CHANNEL LOGIC and OCTAL NHit Cavity Down

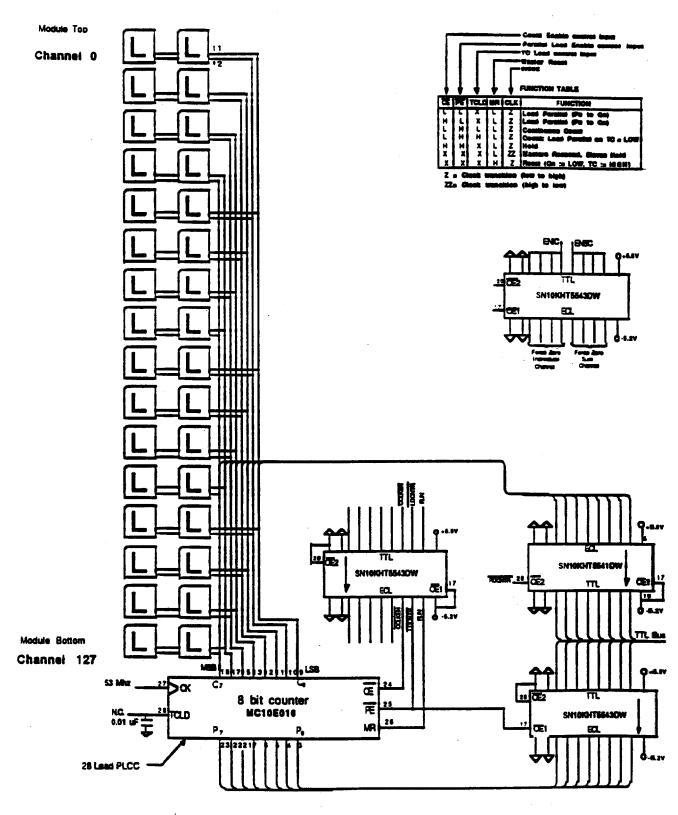


Part Number IC-04

IC-04 Package Dimension Diagram Notes.

1. All dimensions are in mils. (Min/Max)

Created 5-18-89
Revised 6-30-89
Merle Haldeman / Jim Hoff



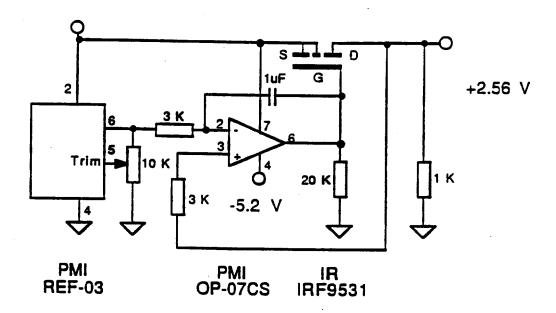
Postamp / Comparator (Discriminator) Module Test Generation

Merie Haldeman 3-27-89 Revised 9-19-89

SSD: POSTAMP/COMPARATOR Module 2.5 Volt Reference Voltage for IC-03 A/D Chip

Merie Haldeman 9/22/89

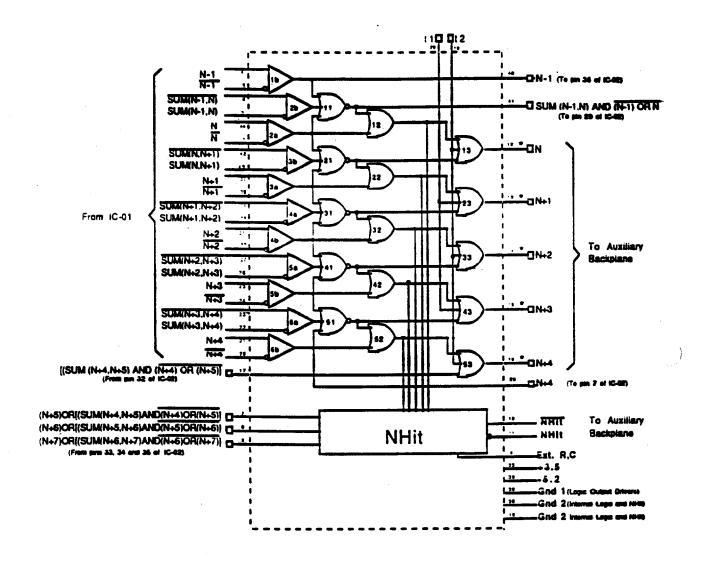
The IC-03 D/A Chip utilized for setting threshold voltages on the P/C Module requires a 2.5 volt reference voltage capable of delivering 3.5 mA per package. With the maximum requirement of 64 packages (256 D/A's) the load on the reference could be as much as 224 mA. One possible design utilizes a voltage reference as the basic stabilizing element, as illustrated below, followed by an opamp and MOSFET for buffering the output.



This basic circuit, with proper heat sinking, should be capable of handling loads up to 6 amperes. In our application, the dissipation should not exceed 600 mW during normal operation.

IC-04: SSD 5-Channel Logic and Octal NHit

Part Number IC-04 V2.0



☐ ECL Levels

		IN		DUTPUTS		
N	SUMIN.N+1)	N+1	SUM(N+1.N+2)	N+2	N+1	N+1 OR P***
X	X	1	X	X	1	1
0	1	0	х	x	1	1
x	×	0	1	0	1	

All other input conditions produce zero outputs X = Don't Care

Power dissipation 350 mW Outputs unloaded.

Power dissipation 500 mW All outputs loaded with 100 ohms to -2.0 Volts.

N	
N+1	
N+2	
N-4	
CASE 1	CASE 2

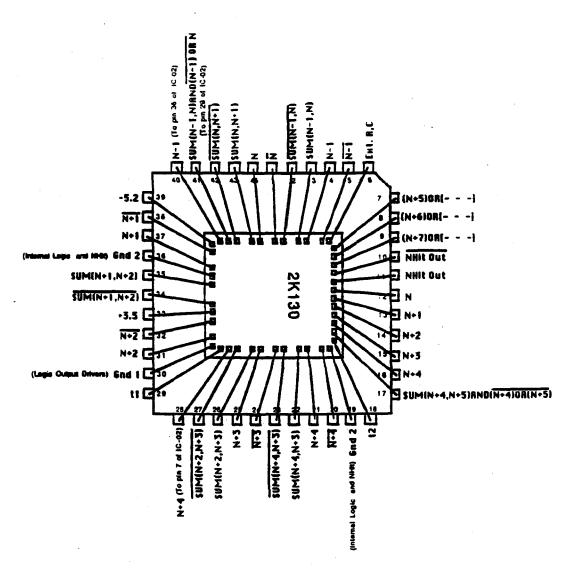
- o Location of particle in SSD
- , Signals to NHit
- · Signals to Auxiliary Backplane

Revised 10-3-69 Marie Holdenton / Jim Half

IC-04: SSD 5-CHANNEL LOGIC & OCTAL NHIT Cavity Down

Thermally Enhanced, 44 Lead Plastic Chip Carrier

Part Number 1C-04, U2.0



BOTTOM VIEW

Created 8-28-89
Revised 10-3-89
Marke Maideman J. Jim Mol

Module Pinout

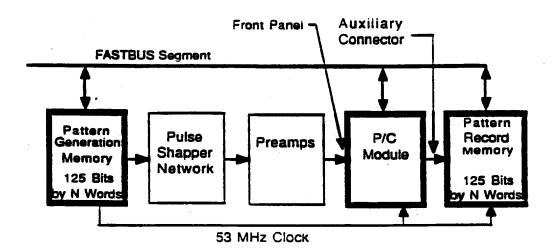
(Viewed from Front of FASTBUS Crate)

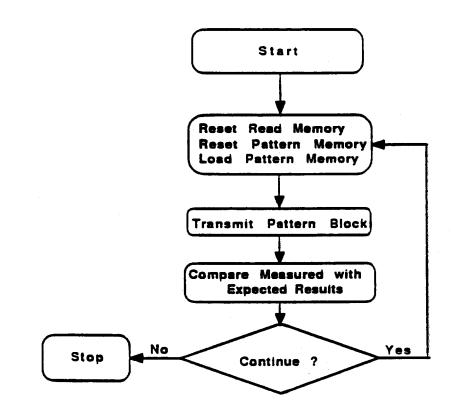
C01	53 MHz, 01 Clock	B01	Post / Comp Ch-01	A01	Post / Comp Ch-00
C02	GND	B02	Post / Comp Ch-03	A02	Post / Comp Ch-02
CO3	PA / E Spare 0	B03	Post / Comp Ch-05	A03	Post / Comp Ch-04
C04	PA / E Spare 0	B04	Post / Comp Ch-07	A04	Post / Comp Ch-06
C05	PA / E Spare 0	B05	Post / Comp Ch-09	A05	Post / Comp Ch-08
C06	PA / E Spare 0	B06	Post / Comp Ch-11	A06	Post / Comp Ch-10
C07	PA / E Spare 0	807	Post / Comp Ch-13	A07	Post / Comp Ch-12
C08	Reset	808	Post / Comp Ch-15	80A	Post / Comp Ch-14
C09	·	8 09	Post / Comp Ch-17	A09	Post / Comp Ch-16
C10		B10	Post / Comp Ch-19	A10	Post / Comp Ch-18
C11		B11	Post / Comp Ch-21	A11	Post / Comp Ch-20
C12	Analog Sum 0-	812	Post / Comp Ch-23	A12	Post / Comp Ch-22
C13	Analog Sum 0+	B13	Post / Comp Ch-25	A13	Post / Comp Ch-24
C14	Digital Sum 0-	B14	Post / Comp Ch-27	A14	Post / Comp Ch-26
C15	Digital Sum 0+	B15	Post / Comp Ch-29	A15	Post / Comp Ch-28
C16	Analog Sum 1-	B16	Post / Comp Ch-31	A16	Post / Comp Ch-30
C17	Analog Sum 1+	B17	Post / Comp Ch-33	A17	Post / Comp Ch-32
C18	Digital Sum 1-	B18	Post / Comp Ch-35	A18	Post / Comp Ch-34
C19	Digital Sum 1+	B19	Post / Comp Ch-37	A19	Post / Comp Ch-36
C50	GND	B20	Post / Comp Ch-39	A20	Post / Comp Ch-38
C21	Analog Sum 2-	B21	Post / Comp Ch-41	A21	Post / Comp Ch-40
C22	Analog Sum 2+	B22	Post / Comp Ch-43	A22	Post / Comp Ch-42
C23	Digital Sum 2-	B23	Post / Comp Ch-45	A23	Post / Comp Ch-44
C24	Digitat Sum 2+	B24	Post / Comp Ch-47	A24	Post / Comp Ch-46
C25	Analog Sum 3-	825	Post / Comp Ch-49	A25	Post / Comp Ch-48
C26	Analog Sum 3+	826	Post / Comp Ch-51	A26	Post / Comp Ch-50
C27	Digitati Sum 3-	B27	Post / Comp Ch-53	A27	Post / Comp Ch-52
C28	Digital Sum 3+	828	Post / Comp Ch-55	A28	Post / Comp Ch-54
C29	GND	B29	Post / Comp Ch-57	A29	Post / Comp Ch-56
C30	•	B30	Post / Comp Ch-59	A30	Post / Comp Ch-58
C31	Analog Sum 4-	B3 1	Post / Comp Ch-61	A31	Post / Comp Ch-60
C32	Analog Sum 4+	B32	Post / Comp Ch-63	A32	Post / Comp Ch-62
C33	Digital Sum 4-	B33	Post / Comp Ch-65	A33	Post / Comp Ch-64
C34	Digital Sum 4+	B34	Post / Comp Ch-67	A34	Post / Comp Ch-66
C35	Analog Sum 5-	B35	Post / Comp Ch-69	A35	Post / Comp Ch-68
C36	Analog Sum 5+	B36	Post / Comp Ch-71	A36	Post / Comp Ch-70
C37	Digital Sum 5-	B37	Post / Comp Ch-73	A37	Post / Comp Ch-72
C38	Digital Sum 5+	B38	Post / Comp Ch-75	A38	Post / Comp Ch-74
C39	GND	B39	Post / Comp Ch-77	A39	Post / Comp Ch-76
C40	Analog Sum 6-	B40	Post / Comp Ch-79	A40	Post / Comp Ch-78
C41	Analog Sum 6+	B41	Post / Comp Ch-81	A41	Post / Comp Ch-80
C42	Digital Sum 6-	842	Post / Comp Ch-83	A42	Post / Comp Ch-82
C43	Digital Sum 6+	B43	Post / Comp Ch-85	A43	Post / Comp Ch-84
C44	Analog Sum 7-	B44	Post / Comp Ch-87	A44	Post / Comp Ch-86
C45	Analog Sum 7+	B45	Post / Comp Ch-89	A45	Post / Comp Ch-88
C46	Digital Sum 7-	B46	Post / Comp Ch-91	A46	Post / Comp Ch-90
C47	Digital Sum 7+	B47	Post / Comp Ch-93	A47	Post / Comp Ch-92
C48	GND	B48	Post / Comp Ch-95	A48	Post / Comp Ch-94
C49		849	Post / Comp Ch-97	A49	Post / Comp Ch-96

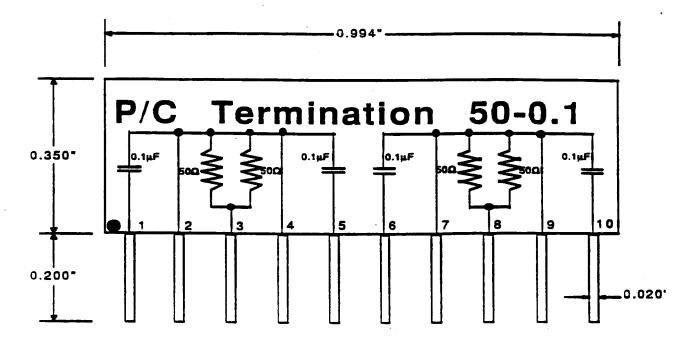
Postamp / Comparator Draft Specification March 30, 1990 12:53

C50	G ND	B 50	Post / Comp Ch-99	A50	Post / Comp Ch-98
C51		851	Post / Comp Ch-101	A51	Post / Comp Ch-100
C52		852	Post / Comp Ch-103	A52	Post / Comp Ch-102
C53		B53	Post / Comp Ch-105	A53	Post / Comp Ch-104
C54		B54	Post / Comp Ch-107	A54	Post / Comp Ch-106
C55		B55	Post / Comp Ch-109	A55	Post / Comp Ch-108
C56		B56	Post / Comp Ch-111	A56	Post / Comp Ch-110
C57		B57	Post / Comp Ch-113	A57	Post / Comp Ch-112
C58		B58	Post / Comp Ch-115	A58	Post / Comp Ch-114
C59		859	Post / Comp Ch-117	A59	Post / Comp Ch-116
C60		B60	Post / Comp Ch-119	A60	Post / Comp Ch-118
C61	GND	B 6 1	Post / Comp Ch-121	A61	Post / Comp Ch-120
C62		B62	Post / Comp Ch-123	A62	Post / Comp Ch-122
C63	GND	B63	Post / Comp Ch-125	A63	Post / Comp Ch-124
C64	VCC, +5.0 Volts	B 64	Post / Comp Ch-127	A64	Post / Comp Ch-126
C65	VEE. - 5.2 Volts	B65	GND	A65	VEE 5.2 Volts

P/C Module Test Scheme







Specifications:

Physical Requirements

Maximum Package Height:

0.350"

Maximum Package Length:

1.000"

Maximum Package Thickness: 0.100"

Package Marking: "P/C TERMINATION 50-0.1"

Electrical Requirements

Resistors

Value:

50Ω, +/- 2%

Power:

100 mW @ 70 C

TCR:

+/-100PPM

Ratio Match between all four resistors +/-1%

Capacitors

Dielectric Type:

Z5U

Value:

0.1μF, +80,-20%

Working Voltage:

25 Volts



January 4, 1991

TO: FROM: Distribution

Carl Swoboda

SUBJECT:

Hardware Description

The attached document is the "as built" hardware description for the SSC DeLay/Encoder module. Please add this document to your SSD Readout System binder.

Distribution: David Christian Brad Cox (E771) Peter Garbincius Franco Grancagnolo (E771,MS219) Hector Gonzalez Bill Haynes Rick Kwarciany Wolfgang Kowald (E771) Mark Larwill Cash McManus (E771) Garry Moore Tom Nash John Peoples **Ruth Pordes** Matteo Racagni (E771) Robert Trendler Ken Treptow

HN 101



DELAY/ENCODER

HARDWARE DESCRIPTION

H.L. Gonzalez, J. Chramowicz, R. Reitz November, 1990

Table of Contents

1.	General Information	3
1.1.	Purpose	3
1.1.1.		3
1.2.	Application	5
1.3.	Packaging	5
1.4.	Power Requirements	5
1.5.	Cooling Requirements	
2.	Theory of Operation and Operating Modes	5
2.1.	Delay	6
2.2.	Encoder	6
3.	Input/Output Specifications	
3.1.	Communication Interfaces	8
3.1.1.	PostAmp/Comparator Port	8
3.1.2.	Sequencer Port	8
3.1.3.	Front Panel	8
4.	Initialization	
5.	Module Diagnostics	
5.1.	Hardware Test	
5.2.	System Test	
6.	Appendix A1	
7.	Appendix B1	3
8.	Appendix C1	4
9.	Appendix D - Figures and Timing Diagrams	
10.	Appendix E - State Machine and PAL Equations	
11.	Appendix F - Parts List	
12.	Appendix G - Circuit Diagrams	

1. General Information

1.1. Purpose

The front end readout electronics for the Silicon Strip Detector is designed to process data at the RF bucket frequency, 53MHz. The Delay/Encoder(DE) module has been specified to accept data at 53MHz, provide a delay mechanism while a trigger decision is made, and generate an address hit list upon a Level 1 accept signal. A simplified block diagram is provided in Figure 2.

The delay element continuously stores data while the level 1 system is processing data corresponding to previously stored events. The delay is implemented in RAM and it is required for the control system to map the level 1 decisions into an eight bit address. The current implementation assumes that processing of an event takes about 1µsecond from the time that it is loaded into the DE. It is mandatory that the event acceptance be time ordered and the decision time be fixed with respect to the event occurrence. The address of accepted events is broadcasted by the Master Timing Controller to all Sequencer modules in the system and each Sequencer addresses the DE in its crate. The addressing mechanism triggers the DE to read the event from memory and transfer it to the encoder section.

The data encoding scheme uses the trigger bucket and the previous bucket simultaneously to generate an address hit list. A flag is asserted whenever the previous bucket has the bit set for the address being output. The address hit list is transmitted synchronously to a crate Sequencer module which serves as a crate controller and event builder for two planes of silicon strip data. The Sequencer is capable of transmitting hit data over fiber optic at 40Mbytes/sec or read out by a Fastbus master.

This document includes figures and timing diagrams intended to simplify the specifications. In some cases, specifically the timing diagrams, the information is an attempt to specify the module and its interface with other system components.

1.1.1. Silicon Strip Readout System

This section presents a simplified block diagram of the silicon strip readout system. Figure 1 shows the interconnection of all the modules that are referenced in this document. A brief description of each module follows.

- PC PostAmp/Comparator board, 12 per crate. Processes 128 pre-amp silicon strip signals, outputs discriminated data to the Delay/Encoder and outputs analog and digital sums to Level 1.
- DE Delay/Encoder board, 12 per crate. Provides event buffering for the PC discriminated data and for level 1 accepted event transmits a hit list to the Sequencer.
- SEQ Sequencer board, 1 per crate. Fans out system clock to PC and DE, initiates the encoding of a event, stores, pipelines and transmits encoded events to the next level. The events can be readout by a FASTBUS master.
- FSCC- Fastbus Smart Crate Controller board, 1 per crate. Initializes the crate by exercising control over the SEQ, runs local diagnostics and provides an alternate data path to readout events.
- MTC- Master Timing Control board, 1 per silicon strip readout system. The MTC synchronizes the 12 SEQ in the system by providing timing and control. Some of the functions that it performs are listed below:
 - Distributes the RF clock to all SEOs.
 - Maps a level 1 accept signal into an address of the DE memory and transmits addresses to all SEQs.
 - Queue level 1 accepted events.
 - Controls the write enable signal for the DE.
 - Responds to READY and ERROR condition from the SEQs.
 - Interface with the overall experiment controller.
 - Synchronize System.

The readout system consists of 12 readout crates and a control crate that contains the MTC and other special modules. Each of the readout crates processes two planes of silicon strip data. Data processing is done in groups of 128 strips by a PC and DE pair. The 12 DEs in a crate send data, in parallel, to the crate SEQ. For a formal description of the system refer to the 'Silicon Strip Readout Implementation Plan' document.

In the context of this specification an event is the output of the PC and they are generated every 18.9nanoseconds.

1.2. Application

The DE is being designed for the Silicon Strip Readout System for E771 and E789. The function of the module is hardwired and there is no other application for it beyond the ones described on this document.

1.3. Packaging

The board is a single width FASTBUS module that does not contain a FASTBUS interface.

1.4. Power Requirements

The maximum and typical current for the module are listed below.

Voltage	Current Max.	Typical Current
-5.2V	17A	14A
-2.0V	6A	6A
+5.0V	<.5A	

The typical power dissipation for the module is 85 W. For protection fuses and tranzsorbs are used for each power supply. The recommended number of fuses is: -5.2v - three 5A and one 3A, -2.0v - three 3A and 5.0v - one 1/2A.

1.5. Cooling Requirements

The module will operate at the temperature range provided by the FASTBUS cooling system.

2. Theory of Operation and Operating Modes

The DE module is a single width board packaged in FASTBUS that does not implement a FASTBUS interface. The DE accepts PC discriminated data from 128 silicon strips, provides event buffering, encodes and transmits accepted events to a crate SEQ. The module communicates with the PC and SEQ through a special FASTBUS auxiliary backplane. The auxiliary connector signals for the DE are described in Appendix A.

The module is divided in two independent functions; the Delay element and the Encoder, see Figure 2. The following sections provide a brief description for each function.

2.1. Delay

The Delay element receives 128 channels of discriminated data from the associated PC and provides buffering for 256 events (~4.8 µseconds). During data acquisition the DE continuously stores data in a FIFO like memory, while the level 1 system is making decisions for previously stored events. The DE does not implement any logic to prevent overwriting interesting events. This operation is delegated to the MTC which keeps track of the system write pointer (for DE) and the queued events. For system implementation reasons, it is mandatory that event acceptance be time ordered and the decision time be fixed with respect to the event occurrence.

The delay element control logic requires that the 53MHz input (CLK2) be a 50% duty cycle clock. The logic splits the 18.9 nanoseconds time slice of each bucket into a read and write periods for a combined bandwidth of 106MHz. The write operation uses an address counter clocked by CLK2 and a write enable signal (WRITE*, asserted low) generated by the MTC and distributed in each crate by the SEQ.

The WRITE* signal is send 128 cycles before the SYNC* pulse. The DE retime the signal with the SYNC* to synchronize the start of event acquisition, see timing 2. The DE starts writing data synchronously with SYNC*, but stops writing data asynchronously when WRITE* is deasserted. The DE will track their synchronization by checking that the write address is zero when the SYNC* signal is asserted. Note that prior to the assertion of WRITE* the DEs had been reset, which forces the write address to zero.

The readout of an event occurs when the MTC receives an accept pulse from the level 1 trigger system. The MTC maps the pulse into an address for the DEs memory and sends the address to all SEQs in the system. The address generated by the MTC shall correspond to the previous bucket location. The previous and accepted buckets are loaded into registers and the Encoder is enabled to begin encoding that particular event.

2.2. Encoder

The Encoder is a simultaneous two bucket hit-list address generator. The encoding is performed in two stages, byte and bit levels, see Figure 3. At load time, the byte encoder performs byte integration, see Figure 4. The output of this process is a 16-bit word with a bit set for bytes with hit channels. At encoding time the byte encoder sequentially selects bytes to be

processed by the bit encoder. The bit encoder (block ENCODER-8) loads the input data when ready and outputs a byte wide address stream of asserted bits. The encoded address is formed by concatenating the byte address with the bit address. In addition the bit encoder sets a flag (DATA0) whenever the previous bucket has a hit for the address being output. The hit list is generated from low to high address and no hit count is generated by the DE. An example of byte encoding is shown below:

Bit # Bucket	Previous Bucket	Trigger Bucket	Hit Type	Bit ADD (HEX)	Flag
7	1	0	Α	7	1
6	0	0	-	-	٠ ـ
5 -	0	1	В	5 .	0
4	1	1	С	4	1
3	. 0	0	-	•	_
2	0	0	-	-	-
1	1	1	С	1	1
0	0	1	В	0	Ō

Note: The encoder never looks at addresses without hits, this is represented with "-".

The option to remove type A hits is implemented on the prototype. There are two options for the address hit list data transfer, 53MHz or 26.5MHz, CLK2 and CLK3 respectively. These options are switch selectable for each DE. Currently only the 26.5MHz transfers have been tested and the present version of the SEQ does not support the 53MHz transfer rate.

From the encoding table shown above two modes of operation are derived: Mode 1 in which type A, B and C hits are included; Mode 2 where type B and C hits are included.

3. Input/Output Specifications

The DE is a two port module, PC port and a SEQ port, See Figure 2. Both of these ports are implemented on an application specific Fastbus Auxiliary backplane that pairs a PC with a DE and has separate connections between each DE and the SEO.

3.1. Communication Interfaces

3.1.1. PostAmp/Comparator Port

The PC port is a 128 bit uni-directional single-ended ECL connection from a PC to the associated DE. Synchronization of this port is controlled by the SEQ supplied CLK1 and CLK2 clocks. CLK1 is remotely programmed through FASTBUS and the rising edge is used by the PC to latch the silicon strip discriminated data. CLK2 is referenced (delayed) to CLK1 such that the PC output data is valid while the DE is asserting the Write* signal for the memories, see Timing 1. It is required that data on this port be valid for at least 12 nanosececonds simultaneously at all DE in a crate.

3.1.2. Sequencer Port

The Sequencer port is the access port for the SEQ to readout the level 1 accepted events. This data port is a byte wide point-to-point connection designed to support a 53MHz data transfer rate. Currently this port is operated a 26.5MHz.

The port provides an address bus, a data bus and control signals. To initiate a transfer the Sequencer supplies the DE with an event address and asserts the Add_Valid signal. After a fixed delay the Encoder will assert a Data_Valid signal (if hits present) and start transmitting the address hit list to the SEQ until completion. The data transfer is synchronous with CLK2 or CLK3 depending on the user selected encoder operating frequency. A non-detailed timing diagram is provided in Timing 4.

3.1.3. Front Panel

The DE front panel is intended to provide information that will help diagnose data encoding problems, refer to Figure 5 for the layout of the front panel. The front panel provides the byte mask (B1_Byt(0:7) and B2_Byt(0:7)) which describes the bytes that have hits. Note that the byte mask provides a bit for each of the 16 bytes of the 128 channels. In addition the front panel provides the bytes that will be loaded next by the Bit_Encoder (TB(0:7) and RPB(0:7)). This information combined with the signal Clk_Byt* provides everything that is required to trace the encoding operation of the DE. Description of the front panel signals is provided on appendix A.

Other signal provided are TC*, 53M* and a sync error led.

4. Initialization

Initialization of the DEs is achieved by deasserting the Write_En* signal and pulsing the SSD Reset signal. Then the MTC initiates the enable of the write process and after the appropriate delay the enable of the Level 1 system. The DE will start writing data synchronously after receiving Sync* when the Write _En* signal is asserted.

After reset, the write counter points to location zero, the Encoder is in the ready state and all control signals driven by the DE are negated. The read counter is not initialized because it is loaded on demand when an event is accepted.

5. Module Diagnostics

5.1. Hardware Test

The DE does not implement any internal diagnostic tests or FASTBUS interface to access it's memory. The decision of excluding these features is based on timing and power considerations.

The Test Stand Module (TSM) is the test module used to debug the DE. The TSM implements a 256 x 128 memory used to emulate the PC output port and one port of the SEQ. The TSM is operated by a FASTBUS master, i.e. the FSCC. In brief the user will load the memory, initiate the data transfer from TSM to DE and then request events to be encoded by the DE (from it's memory). The encoded event is read out from the TSM and compared with the expected result. A detailed description of the DE software diagnostics is provided in the Software Document PN434.

5.2. System Test

For system diagnostics the PC provides a maximum of 256 data patterns generated by a counter. The counter can be programmed to count or hold the loaded value. The data is stored by the DE into it's memory an events to be encoded are requested through the SEQ. Synchronization is achieved by the initialization of the SSD system and from the match between the 256 different patterns and the 256 memory locations on the DE.

6. Appendix A

This appendix describes the DE auxiliary connector signals used on the silicon strip readout crates and the signals provided in the front panel. In addition any other signals of interest are described.

A.1 Auxiliary Connector

CLK1	- A 53MHz clock driven by the SEQ and used by the
·	PC to latch data. This clock is remotely programmable through the FASTBUS port on the SEQ.
CLK2	- A 53MHz clock driven by the SEQ. The clock is a delayed version of CLK1 used to synchronize the write process in the DE with the output data of the PC, to generate internal timing and as a reference when transmitting data to the SEQ at 53MHz.
CLK3	- A 26.5MHz clock driven by the SEQ. The clock used to transmit data to the SEQ. The DE samples the 26.5MHz on the backplane with the internal 53MHz clock.
DI(0:127)	- Input discriminated data driven by the associated PC. A 100 ohms termination is provided by the DE.
Address(0:7)	- The address bus (bussed to all DE) driven by the SEQ to transfer event addresses to the DE.
Add_Valid	- Signal driven by SEQ to validate ADD(0:7).
Write_En*	- Write enable signal distributed on the backplane by the SEQ. The signal is controlled by the MTC or through a FASTBUS register on the SEQ.
Sync*	- Synchronization signal generated by the MTC and used by the DEs to test write counter

synchronization at each zero crossing. If a DE has a

write counter different from zero then it is out of synchronization.

Sync_Err

- Signal asserted by a DE that is out of synchronization and received by the SEQ. The signal is wire-ored on the backplane.

Reset

- Reset signal distributed on the backplane by the SEQ.

Data_X(0:7)

- Encoded hit list data bus for Delay/Encoder X, where X is a hex number assigned to each DE. Terminated by the SEQ.

Data_ValidX

Data valid signal asserted by Delay/Encoder X, where X is a hex number assigned to each DE. Terminated by the SEQ.

A.2 Front Panel Signals

B1_Byt(0:7) * - This are the lower 8 bits of the byte encoding process implemented by the logic in Figure 4.

B2_Byt(0:7)* - This are the upper 8 bits of the byte encoding process implemented by the logic in Figure 4.

TC*
- This signals is asserted low every time that the write counter of the DE is at FFh. This signal should remain at a fixed reference relative to the system Sync signal.

53M* - A buffered inverted sample of the 53MHz clock received by the DE from the backplane.

Error - RED LED that is on when the DE detects that is out of synchronization with respect to the Sync signal on the backplane.

Clk_Byt* - Clock pulse that signals that a new byte is being loaded into the Bit-Encoder. Also the lowest bit in

B1_Byt(0:7), B2_Byt(0:7) will be set, meaning that the corresponding byte is being processed.

TB(0:7)*

The Trigger bucket loaded into the Bit_Encoder when Clk_Byt* was pulsed.

RPB(0:7)*

The Previous bucket loaded into the Bit_Encoder when Clk_Byt* was pulsed.

7. Appendix B

This appendix covers the switches and switch setting for the DE. The switches or jumper (label as TP) points are implemented with wire-wrap pins to limit the problems of wrong set ups. For the operation mode refer to Section 2.2.

SW1 Selects for the encoding clock (same clock used to transfer data to the SEQ). The default is pin-2 to pin-1, the 26MHz is selected SW2 Selects the clock that increments the write counter. The default is connect pin-2 to pin-3, the write counter is incremented with a signal derived from the write signal going to the memories. SW3 Selects the select line for the address mux. The default is pin-2 to pin-3, use CLKB4 which is a 53MHz signal. SW4 This switch was implemented to disable the write signal during the time that an event was being read out into the registers (the write would be disable for 40nsec. approximately). The default is the open position, this is no wire.

Mode 1 Setting

TP1 and TP2 shorted, this allows both buckets to be included on the generation of the byte mask shown in Figure 4. In addition the following pairs on TP must be shorted: TP4-TP8, TP5-TP9, TP6-TP10, TP7-TP11, TP12-TP16, TP13-TP17, TP14- TP18, TP15-TP19.

Mode 2 Setting

TP1 and TP2 open, this disables the previous bucket from being included in the generation of the byte mask. In addition the set of pins mentioned in Model 1 (TP4 TP19) must be open. The following pins are to be tied to an ECL high; TP4, TP5, TP6, TP7, TP12, TP13, TP14 and TP15.

8. Appendix C

Encoder Module Pin List (Viewed From Front of Crate-10/1/90)

C01-N/C	B01-Post/Disc Ch.00	A01-Post/Disc Ch.01
C02-GND	B02-Post/Disc Ch.02	A02-Post/Disc Ch.03
C03-N/C	B03-Post/Disc Ch.04	A03-Post/Disc Ch.05
C04-GND	B04-Post/Disc Ch.06	A04-Post/Disc Ch.07
C05-GND	B05-Post/Disc Ch.08	A05-Post/Disc Ch.09
C06-GND	B06-Post/Disc Ch.10	A06-Post/Disc Ch.11
C07-GND	B07-Post/Disc Ch.12	A07-Post/Disc Ch.13
C08-Reset	B08-Post/Disc Ch.14	A08-Post/Disc Ch.15
C09-Sync	B09-Post/Disc Ch.16	A09-Post/Disc Ch.17
C10-GND	B10-Post/Disc Ch.18	A10-Post/Disc Ch.19
C11-GND	B11-Post/Disc Ch.10	
C12-Sync Err	B12-Post/Disc Ch.22	A11-Post/Disc Ch.21
C12-Sylic Err C13-GND	B13-Post/Disc Ch.24	A12-Post/Disc Ch.23
	B13-Post/Disc Ch.24 B14-Post/Disc Ch.26	A13-Post/Disc Ch.25
C14-GND		A14-Post/Disc Ch.27
C15-GND	B15-Post/Disc Ch.28	A15-Post/Disc Ch.29
C16-GND	B16-Post/Disc Ch.30	A16-Post/Disc Ch.31
C17-GND	B17-Post/Disc Ch.32	A17-Post/Disc Ch.33
C18-GND	B18-Post/Disc Ch.34	A18-Post/Disc Ch.35
C19-GND	B19-Post/Disc Ch.36	A19-Post/Disc Ch.37
C20-GND	B20-Post/Disc Ch.38	A20-Post/Disc Ch.39
C21-Hit Data 0	B21-Post/Disc Ch.40	A21-Post/Disc Ch.41
C22-Hit Data 1	B22-Post/Disc Ch.42	A22-Post/Disc Ch.43
C23-GND	B23-Post/Disc Ch.44	A23-Post/Disc Ch.45
C24-Hit Data 2	B24-Post/Disc Ch.46	A24-Post/Disc Ch.47
C35-Hit Data 3	B25-Post/Disc Ch.48	A25-Post/Disc Ch.49
C26-GND	B26-Post/Disc Ch.50	A26-Post/Disc Ch.51
C27-Hit Data 4	B27-Post/Disc Ch.52	A27-Post/Disc Ch.53
C28-Hit Data 5	B28-Post/Disc Ch.54	A28-Post/Disc Ch.55
C29-GND	B29-Post/Disc Ch.56	A29-Post/Disc Ch.57
C30-Hit Data 6	B30-Post/Disc Ch.58	A30-Post/Disc Ch.59
C31-GND	B31-Post/Disc Ch.60	A31-Post/Disc Ch.61
C32-Hit Data 7	B32-Post/Disc Ch.62	A32-Post/Disc Ch.63
C33-Data Valid	B33-Post/Disc Ch.64	A33-Post/Disc Ch.65
C34-GND	B34-Post/Disc Ch.66	A34-Post/Disc Ch.67
C35-26 MHz Clock	B35-Post/Disc Ch.68	A35-Post/Disc Ch.69
C36-GND	B36-Post/Disc Ch.70	A36-Post/Disc Ch.71
C37-Event Address Valid	B37-Post/Disc Ch.72	A37-Post/Disc Ch.73
C38-Event Address Wrt. En.	B38-Post/Disc Ch.74	A38-Post/Disc Ch.75
C39-GND	B39-Post/Disc Ch.76	A39-Post/Disc Ch.77
C40-Event Address 0	B40-Post/Disc Ch.78	A40-Post/Disc Ch.79
C41-Event Address 1	B41-Post/Disc Ch.80	A41-Post/Disc Ch.81
C42-GND	B42-Post/Disc Ch.82	A42-Post/Disc Ch.83
C43-Event Address 2	B43-Post/Disc Ch.84	A43-Post/Disc Ch.85
C44-Event Address 3	B44-Post/Disc Ch.86	A44-Post/Disc Ch.87
C45-GND	B45-Post/Disc Ch.88	A45-Post/Disc Ch.89
C46-Event Address 4	B46-Post/Disc Ch.90	•
C47-Event Address 5		A46-Post/Disc Ch.91
	B47-Post/Disc Ch.92	A47-Post/Disc Ch.93
C48-GND	B48-Post/Disc Ch.94	A48-Post/Disc Ch.95
C49-Event Address 6	B49-Post/Disc Ch.96	A49-Post/Disc Ch.97
C50-Event Address 7	B50-Post/Disc Ch.98	A50-Post/Disc Ch.99
C51-GND	B51-Post/Disc Ch.100	A51-Post/Disc Ch.101
C52-GND	B52-Post/Disc Ch.102	A52-Post/Disc Ch.103
C53-GND	B53-Post/Disc Ch.104	A53-Post/Disc Ch.105

C54-GND	B54-Post/Disc Ch.106	A54-Post/Disc Ch.107
C55-GND	B55-Post/Disc Ch.108	A55-Post/Disc Ch.109
C56-GND	B56-Post/Disc Ch.110	A56-Post/Disc Ch.111
C57-GND	B57-Post/Disc Ch.112	A57-Post/Disc Ch.113
C58-GND	B58-Post/Disc Ch.114	A58-Post/Disc Ch.115
C59-GND	B59-Post/Disc Ch.116	A59-Post/Disc Ch.117
C60-GND	B60-Post/Disc Ch.118	A60-Post/Disc Ch.119
C61-GND	B61-Post/Disc Ch.120	A61-Post/Disc Ch.121
C62-H53MHZ,Ø2 Clock	B62-Post/Disc Ch.122	A62-Post/Disc Ch.123
C63-L53MHZ,Ø2 Clock	B63-Post/Disc Ch.124	A63-Post/Disc Ch.125
C64-N/C	B64-Post/Disc Ch.126	A64-Post/Disc Ch.127
C65-N/C	B65-GND	A65-N/C

9. Appendix D

Figures and Timing Diagrams

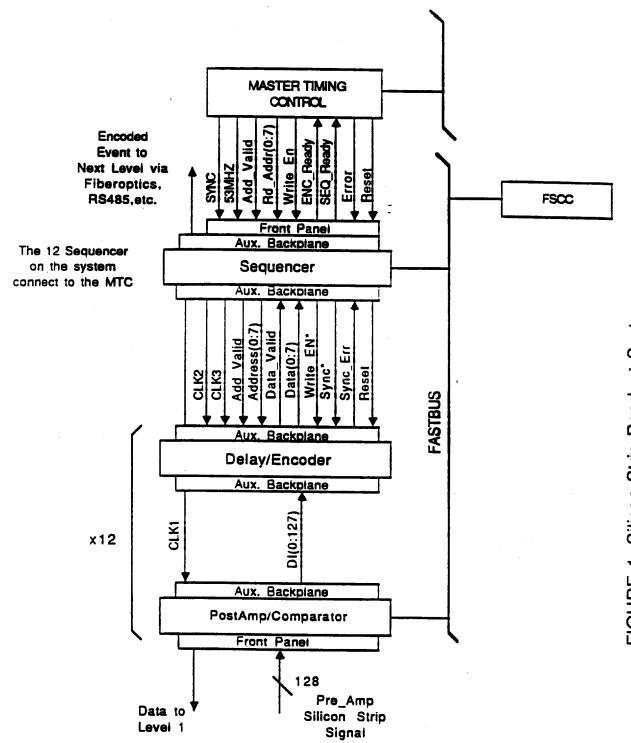
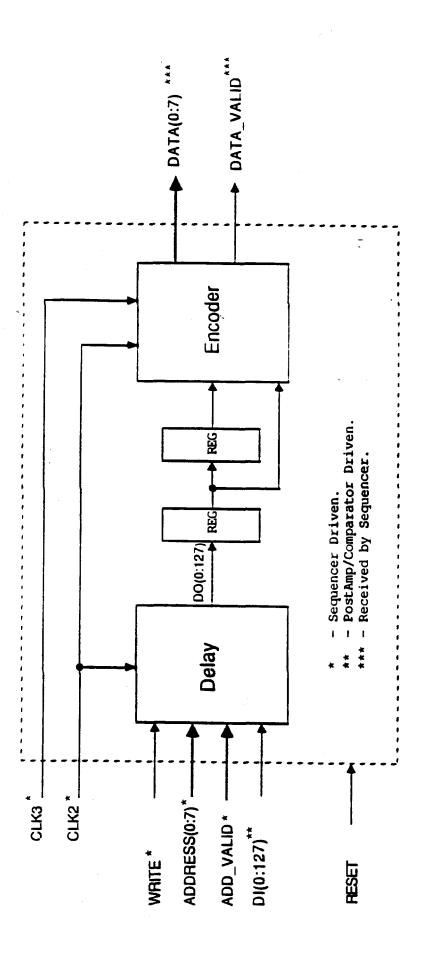


FIGURE 1: Silicon Strip Readout System



SEQ PORT:

WRITE - Write enable for the delay memory.

ADDRESS(0:7) - Accepted bucket address.

ADD VALID - Validates ADDRESS(0:7).

DATA(0:7) - Channel to transmit the address hit list.

DATA_VALID - Enable the Sequencer to clock data into its FIFO.

- PC output data.

PC PORT: DI (0:127)

Figure 2: Delay/Encoder Block Diagram

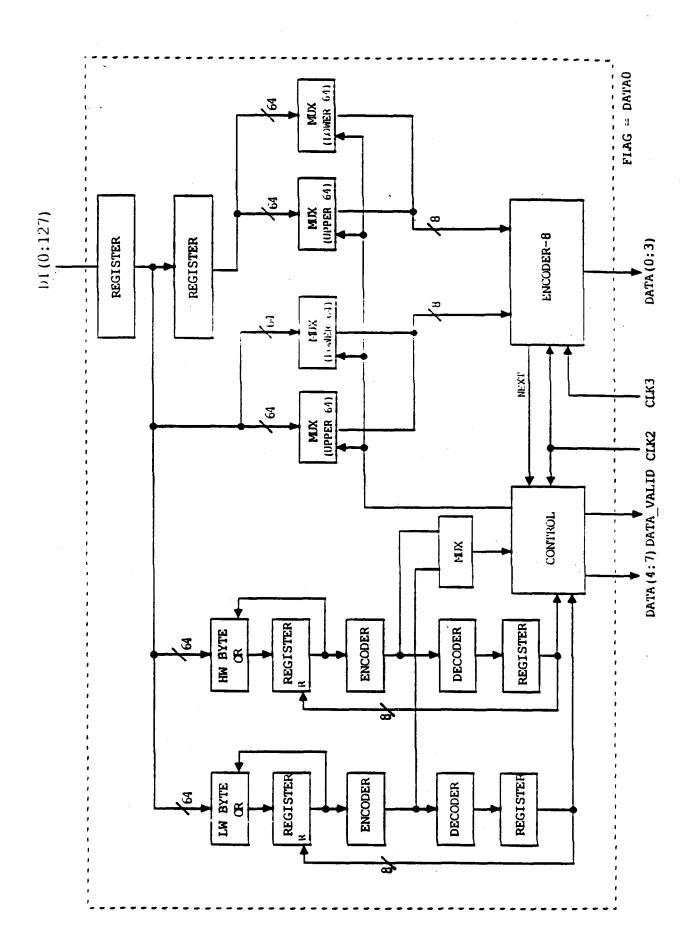


Figure 3: 128-BIT ENCODER

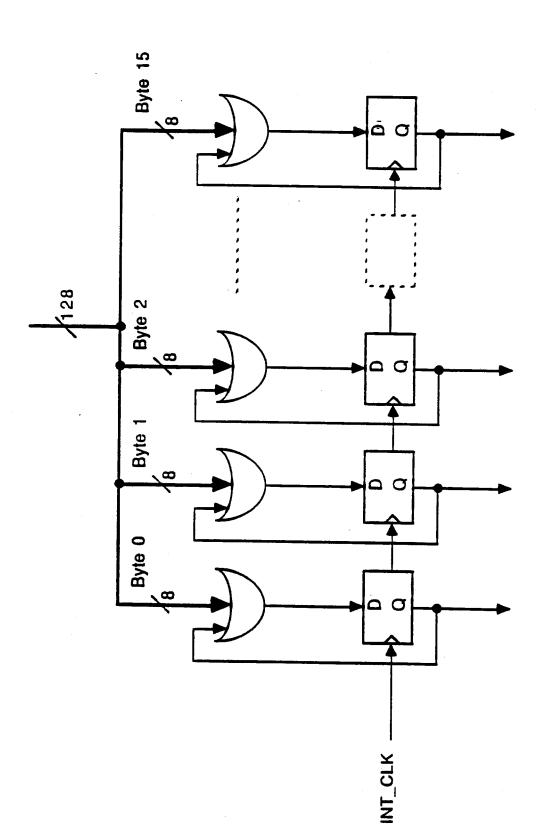
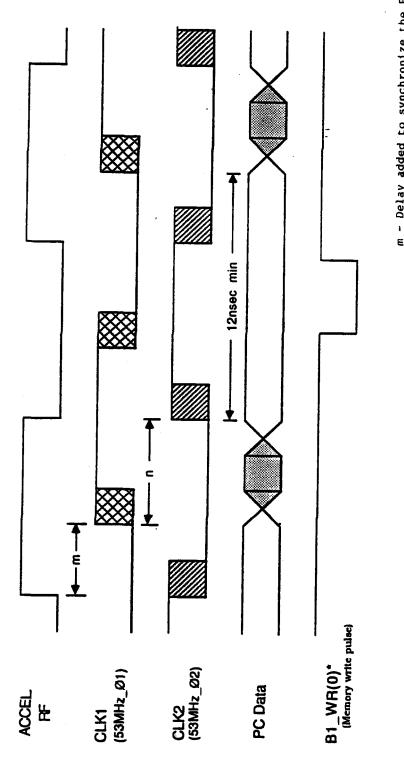


Figure 4: Byte Integration

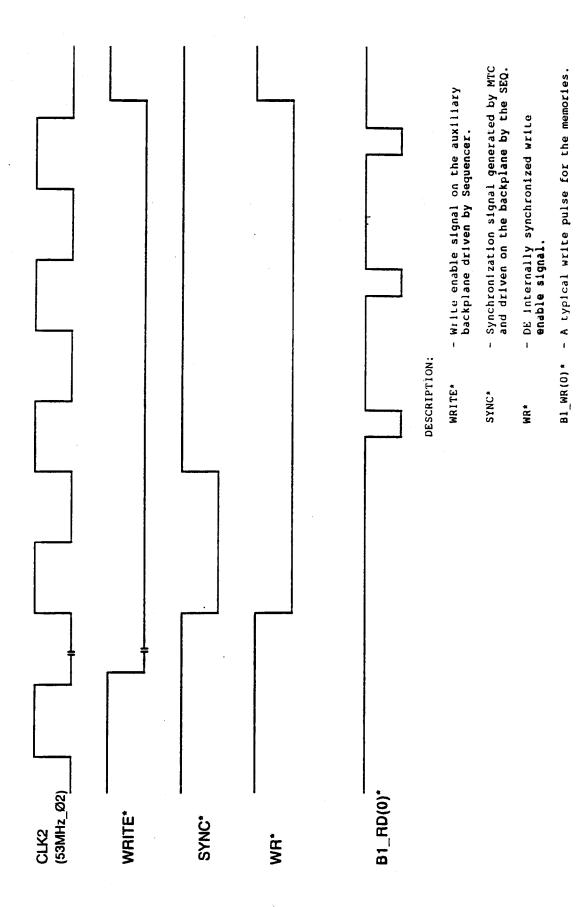


Figure 5: Front Panel Layout

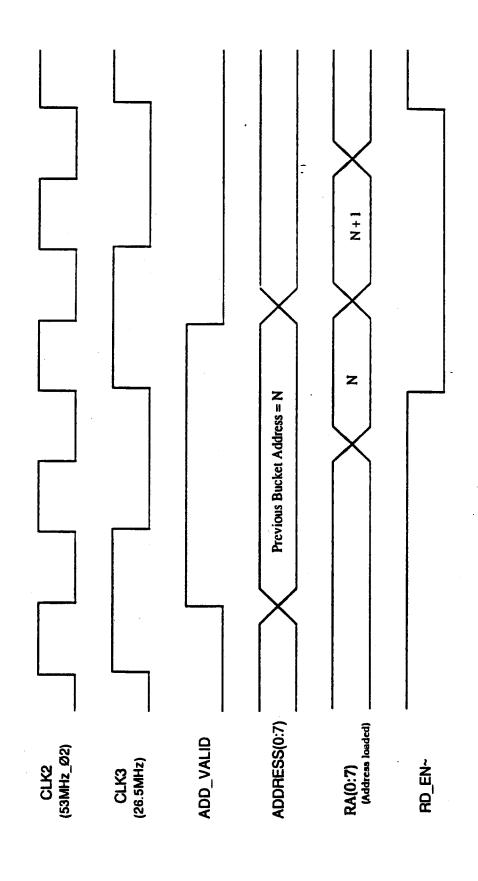


m - Delay added to synchronize the PC to
 the accelerator RF.
 n - Delay added to CLK1 clock to synchronize
 the DE to the PC output data.

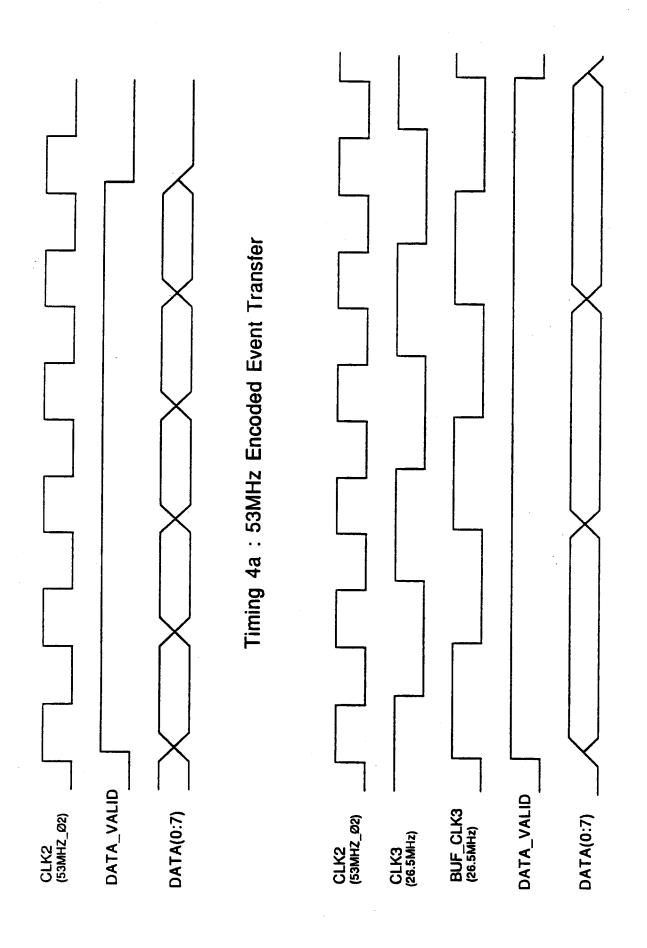
Timing 1: Synchronization of DE to PC.



Timing 2: Write Enable Synchronization.



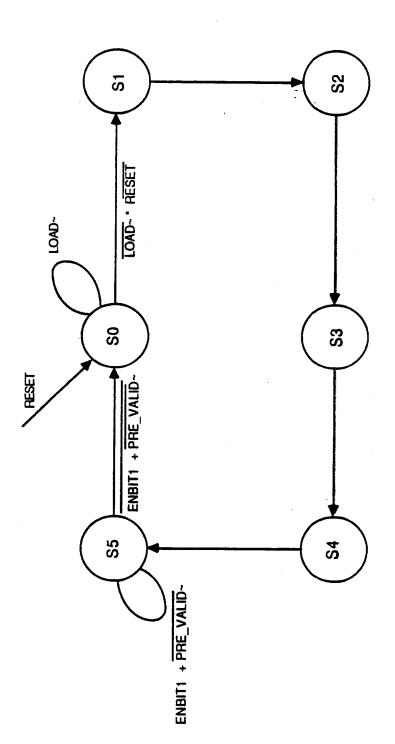
Timing 3: Address Transfer from SEQ to DE.



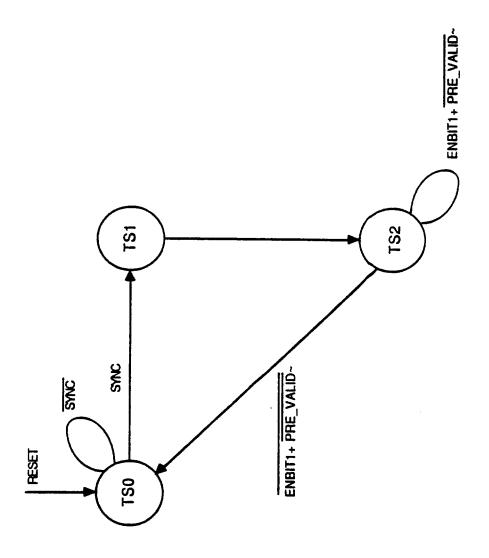
Timing 4b: 26.5MHz Encoded Event Transfer

10. Appendix E

State Machine and Pal Equation Used in DE



ENCODER PRIMARY STATE MACHINE



ENCODER DATA TRANSFER STATE MACHINE

EQUATIONS:

S0 = RESET + S0 * LOAD~ + S5 * (NOT (ENBIT1 + NOT (PRE_VALID~))):;

 $S1 = S0 \cdot (NOT LOAD^{-}) \cdot (NOT RESET);$

S2 = S1;

S3 = S2;

S4 = S3;

S5 = (NOT RESET) * (S4 + S5 * (ENBIT1 + NOT (PRE_VALID~)));

TS0 = RESET + TS0 * (NOT SYNC) + TS2 * (NOT (ENBIT1 + PRE_VALID~)));

TS1 = TS0 * SYNC * (NOT RESET);

TS2 = (NOT RESET) * (TS1 + TS2 * (ENBIT1 + (NOT PRE_VALID~)));

module DE_CONTROL

title 'State Control for the Delay/Encoder

Revisions:

Hector L. Gonzalez January 29, 1990

	DE_CNTRL	DEVICE	'EC20P8M';
"inputs	•		
	S0, S3, S4, S5 RESET SYNC !LOAD !EN_BIT1 !PRE_VALID TS0, TS1, TS2	PIN PIN PIN PIN PIN PIN	1, 2, 3, 11; 9; 10; 13; 14; 1;
"output	,	51%	16, 22, 23;
	PSO, PS1, PS4, FS PTS0, PTS1, PTS2	5 PIN	1, 7, 13, 10; 1, 17, 11;
equatio	ns		
	PS0 = RESET # S0 & !LOA! # S5 & ! (EN	D & !RESET _BIT1 = PRE_VAN	LID) & !RESET;
	PS1 = S0 & LOAD	& !RESET;	
	PS4 = S3 & !RESI	et;	
	PS5 = S4 & !RES: # S5 & (EN_	ET BIT1 = PRE_VAL:	ID) & !RESET;
	PTS0 = RESET # TS0 & :SY1 # TS2 & :(E)		ALID) (!RESET;
	PTS1 = TS0 & SYNC	& !RESET;	
	PTS2 = TS1 & !RES! # TS2 & (EN		LID) & !RESET;
end DE	_CONTROL		

11. Appendix F

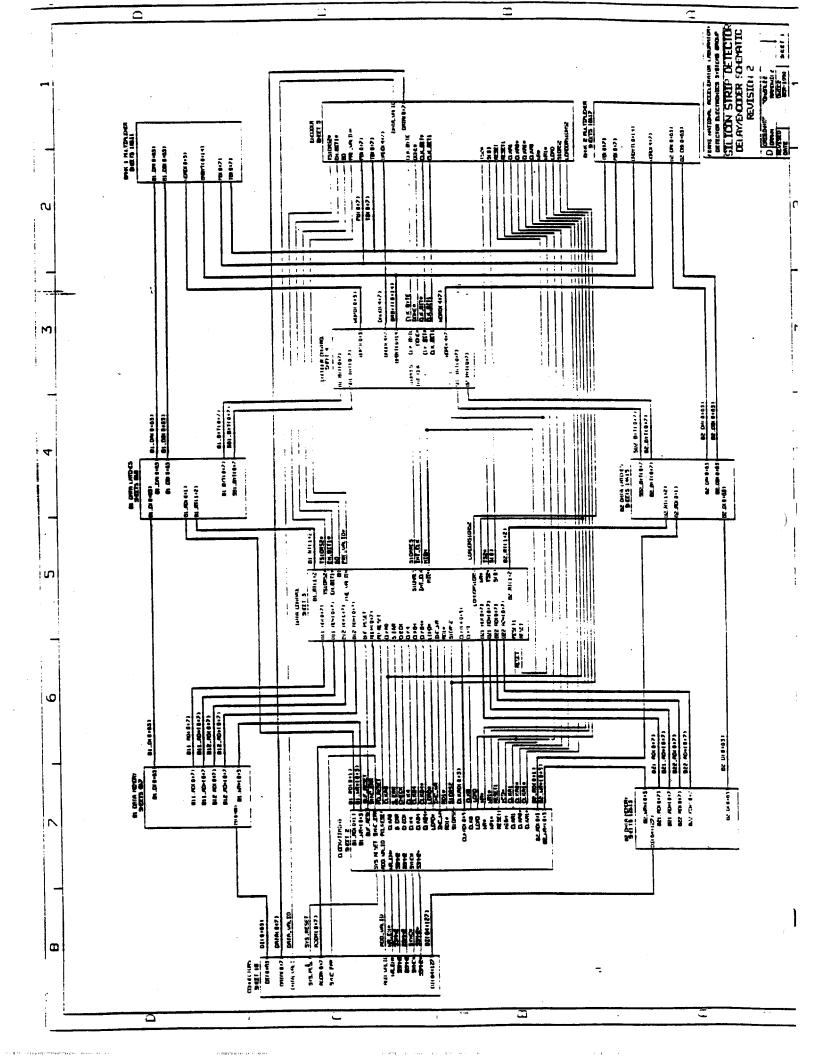
Parts List

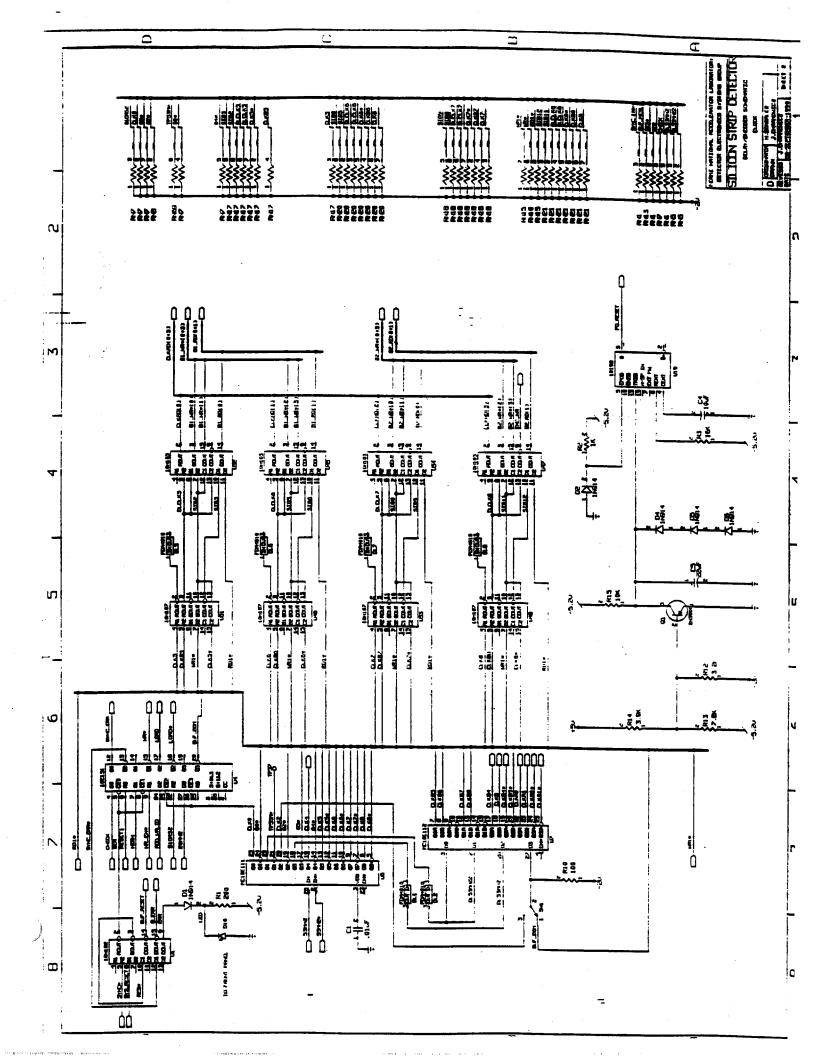
8	כ	2	"	_	و	ĭ		7	٤		Σ	Z	2	2
Quantity/	IEE(mA)	IEE(mA)	IEE(typ)	EE(max	Price /	Cost/	Parts	Spares	Total	Parts	Oty. to	Oty.	O	Total Cost
Board	Typical	Maximum	Total	Total	1000 QIY	Board	Needed	Needed	Needed	on hand	Order	Ordered	Rec'd.	24
														ł
2	151	181	0.30	0.36	\$28.20	\$56.40	48	5	53	49	4	0	0	\$1,494.60
7	20	26	0.14	0.18	\$0.60	\$4.20	168	17	185	161	24	0	0	\$111.00
9	20	26	1.0	0.16	\$0.60	\$3.60	144	14	158	374	-216	0	0	\$94.80
9		26	0.1	0.16	\$0.60	\$3.60	144	14	158	272	-114	0	0	\$94.80
2		35	0.0	0.07	\$0.60	\$1.20	48	S	53	109	-56	0	0	\$31.80
4	2		0.11	0.11	\$0.65	\$2.60	96	10	106	217	.111	0	0	\$68.90
18	-	14	0.2	0.25	\$0.76	\$13.68	432	43	475	79	-318	0	0	\$361.00
-		9	0.05	0.0	\$23.47	\$23.47	N:	21	26	41	.15	0	0	\$610.22
	47	56	0.0	0	\$9.00	\$9.00	24	⊘ i	26	36	.10	0	0	\$234.00
12	4	95	0.5	0	\$1.50	\$18.00	288	21	317	009	-283	0	0	\$475.50
16	45		0.7	6.0	\$1.90	\$30.40	384	n	422		37	0	0	\$801.80
3	5	70	0.1	0	\$12.60	\$37.80	7.2	7	79		52	0	0	\$995.40
9			0.3	0	\$13.76	\$82.56	1.4.1	=	158	162	4	ō	0	\$2,174.08
E		48	0.1	0.1	\$1.35	\$4.05	7.5	ν,	67	. !	.27	0	0	\$106.65
32	42	53	1.3	1.7	\$2.03	\$64.96	168	17	845		4	0	O I	\$1,715.35
3		76	0	0	\$1.50	\$4.50	7.5	7	62		CI	0:	01	
		7.5	0.0	0	\$1.45	\$1.45	کار .	ē	56	- !	. 5	0	0:	\$37 70
C	105	131	0.32	ļ	\$5.10	\$15.30		: .	67	_	8	0:	0	
46		112	4.0	S	\$2.36	\$108.56	1011	<u> </u>	1214	1202	12	0	<u>c:</u>	
G		110	0.5	0	\$3.25	\$19.50	7	7	158		2	0:	c.	
_		42	0.0	0	\$1.00	\$1.00	7.	2	50	:		C ·	3 :	\$26.00
	80	001	0.08	0	\$13.00	\$13 00	27	Cui	26		_	0:	0:	
32	15	175	4.8	io.	58.33	\$266.56	89/	. 77	845	90	-8155	0	01	<u>57.038</u> 85
_	j	21	0.5	0.2	\$30.41	S30 41	CJ:	21	26	35	O	0	0:	\$790 66
_	0	0	0.00	0	\$1.65	\$1.65	- C2:	⊘ i	26	100	-74	0:	0 i	
_	0			0	\$8.00	\$8.00	24	ζ.	26	0	26	0	0	\$208 00
_	0	0	0.0	0	\$8.00	\$8.00	24	8	26		.74	0	0	\$208.00
3		0	0.0	0	\$8.00	\$24.00	72	7	79	78		0	0	\$632.00
-		0	0.0	0	\$8.00	\$8.00	24	2	26	1	7	0	0	\$208.00
8		0	0.00	0	\$0.15	\$1.20	192	6	211	69		0	0	\$31.65
72	0	0	0.0	00.0	\$0.15	\$10.80	1728	17	1901	3000	-1099	0	0	\$285.15
59	0	0	0.0	0.00	\$0.20	\$11.80	1416	142	1558	2500	-942	0	0	\$311.60
-	0	0	0.00	0.00	\$9.50	\$9.50	24	2	26	0	26	0	0	\$247.00
	0	0	0.00	0.00	\$26.00	\$26.00	24	2	26	0	26	0	٥	\$676.00
16		0	0.	0.00	\$0.04	\$0.64	384	38	422	0	422	0	0	\$16.88
	(•	•	000	1000	21 03	200	•	400	•	200	•	~	76 74

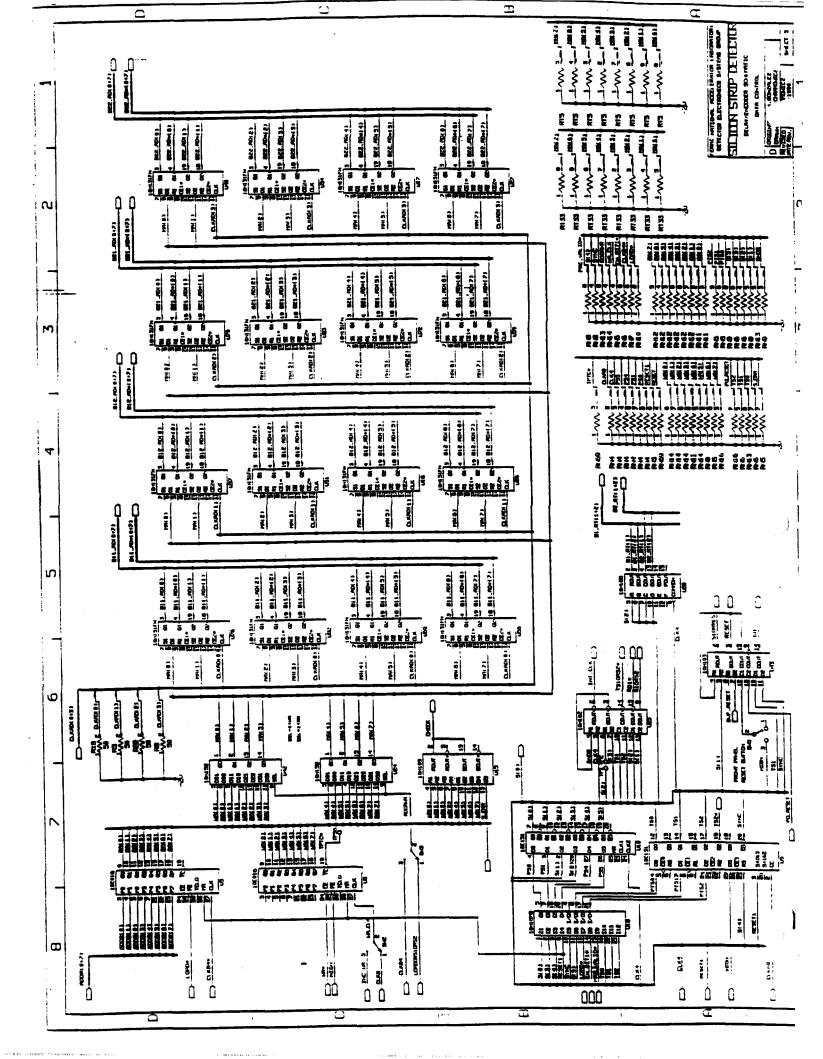
	A	В	၁	O	Е	F	5	H	_	7	¥	1	3	Z	0	Ь
-	Part Number	Quantity/	IEE(mA)	IEE(mA)	(EE(tyb)	IEE(max)	Price /	Cost/	Parts	Spares	Total	Parts	Oty. to	Oty.	Öİ,	Total Cost /
7		Board	Typical	Maximum	Total	Total	1000 City	Board	Needed	Needed	Needed	on hand	Order	Ordered	Rec'd.	24
°.																
4	200 OHM RES.	-	0	0	0.00	0.00	\$0.04	\$0.04	24	2	26	0	26	0	0	\$1.04
4.1	1K OHM RES.	3	0	0	0.00	0.00	\$0.04	\$0.12	72	7	79	0	79	0	0	\$3.16
42	3.2K OHM RES.	1	0	0	0.00	0.00	\$0.04	\$0.04		2	26	0	26	0	0	\$1.04
4 3	3.9K OHM RES.	1	0	0		00.00	\$0.04	\$0.04	24	2	26	0	26	0	0	\$1.04
4 4	7.8K OHM RES.	1	0	0	0.00	0.00	\$0.04	\$0.04		2	26	0	56	0	0	\$1.04
4 5	10K OHM RES.	1	0	0	0.00	00.00	\$0.04	\$0.04	24	8	26		26	0	0	\$1.04
4 6	16K OHM RES.	1	0	0		0.00	\$0.04	\$0.04	24	N	26		26		0	\$1.04
47	20 pF CAP	4	0	Ō		0.00	\$0.20	\$0.80	96	10	106	0	106		0	\$21.20
4 8	KEMET 4.7 of CAP	10	0	0	0.00	0.00	\$0.14	\$1.40	240	24	264	245	19	0	0	\$36.96
4 9	10uF CAP.	1	0	0	0.00	0.00	\$0.75	\$0.75	S	21	26	0	26	0	0	\$19.50
5 0	22UF CAP.		0	0			\$0.75	\$0.75	2	~	26	0		0	0	\$19.50
5.1	47uF CAP.	2	0	0	0.00	0.00	\$0.75	\$1.50	37	S	53		53	0	0	\$39.75
52	1N914 DIODE	7	0	0			\$0.15	\$1.05	168	7	185			0	0	\$27.75
5 3	2N3906 TRANS.		0	0	00.0	0.00	\$0.20	\$0.20	2.2	21	26	36	-10	0;	01	\$5.20
5.4	ICTE-5 DIODE	2	0	0	0 00	i	\$0.75	\$1.50	æ:	S	53	 	53	0	0:	\$39.75
5.5	TP12H9AB SW.	1	0	0	0.00	0	\$4.53	ব ।	Ç1	Ωi	26	31	.5	01	0:	\$117.78
56	275005 FUSE	7	0	0	0.00	0	\$0.75	\$5.25	168	17	185	0	185	01	Ci	\$138 75
5.7	2-331272-2 SOC.	16	0	0	00.0	Oi.	\$0.23	CD :	38.1	38	422	-		01	0:	\$97.06
2 8	40F6261 TEST PT.	37		0		oi	\$0.37	\$13.69	888	80	977	1200	S	0	0	\$361.49
5 9	1447-0475 RED LED		0	0	00.0	000	\$0.20	\$0.20	₹.	€1i	•	0	26	0	O'	
0 9	923CZ5U103M050B	221	0	0		ci	\$0.20	\$44.20	5:304	5.30	5834	4800	1034	0.	C:	
6 1	CIRCUIT BOARD	-	0	0		01	\$400.00	\$400.00	2.	0	24	0	2	<u> </u>	.	29.600.00
6 2	FRONT PANEL		0	0			\$31.00	\$31.00	21	0		0	24	0	0:	8744 00
6 3	PNL. MTG. HDWR.	_	0	0	00.0	00 0	\$1.00		C/1	0	24	0		01	0	\$24.00
6 4																
6 5	IEE Typical =	14.71	Amps	IEE Max =		Amps	Cost/Bd.=	1,437.41			İ					
	Power Typ =	9/	Warrs	Power Max-	94	Walls				Ī			i	:	:	1
6 7										1						
9	Last Updated:	17-0ct		Total # of	Boards	24	Til. Cost =	34,497.84							7	

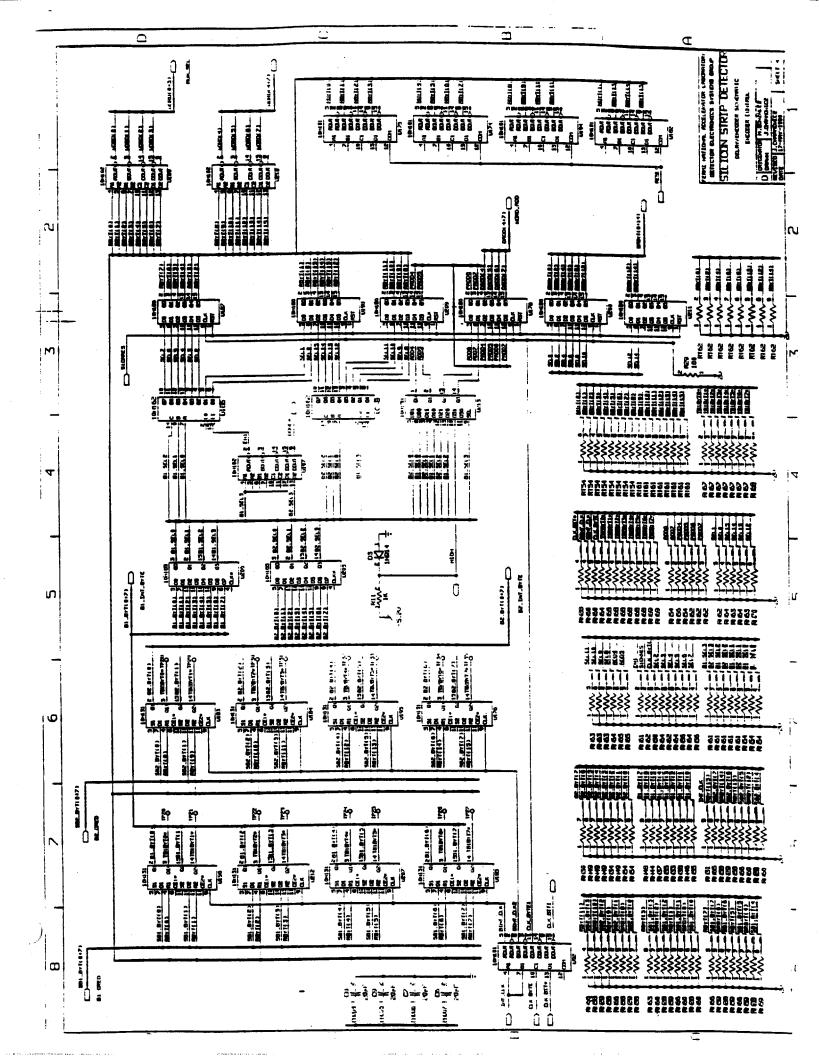
12. Appendix G

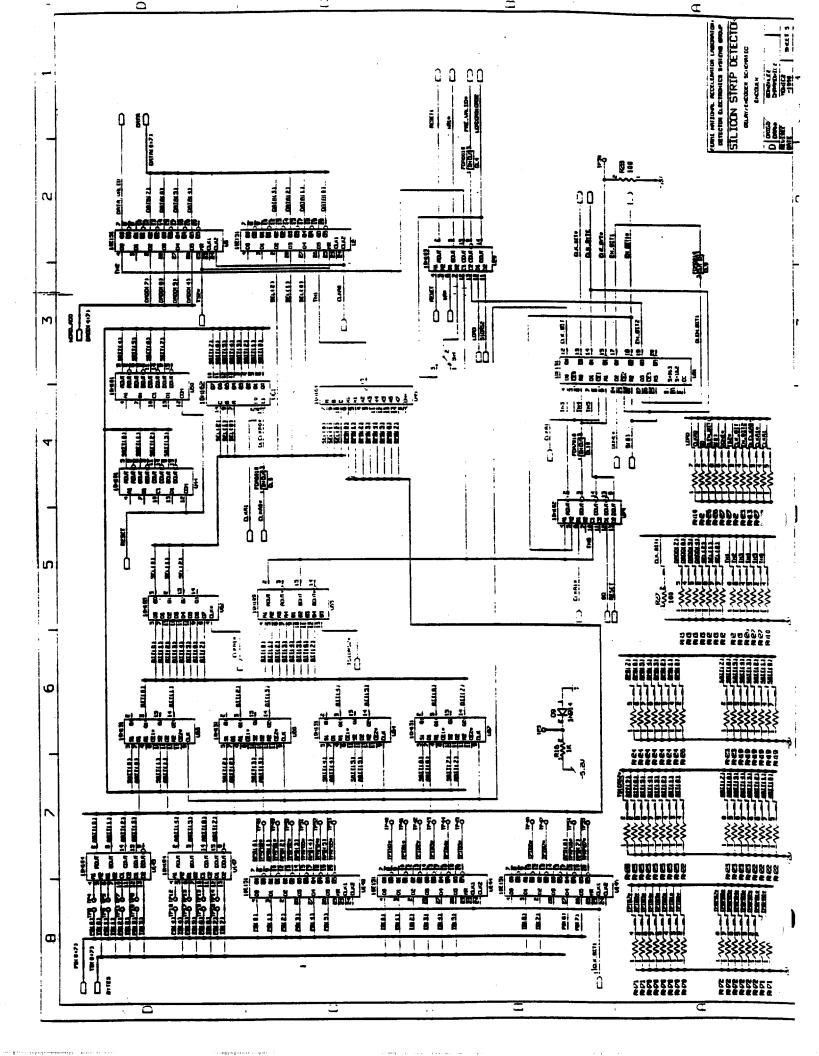
Circuit Diagrams

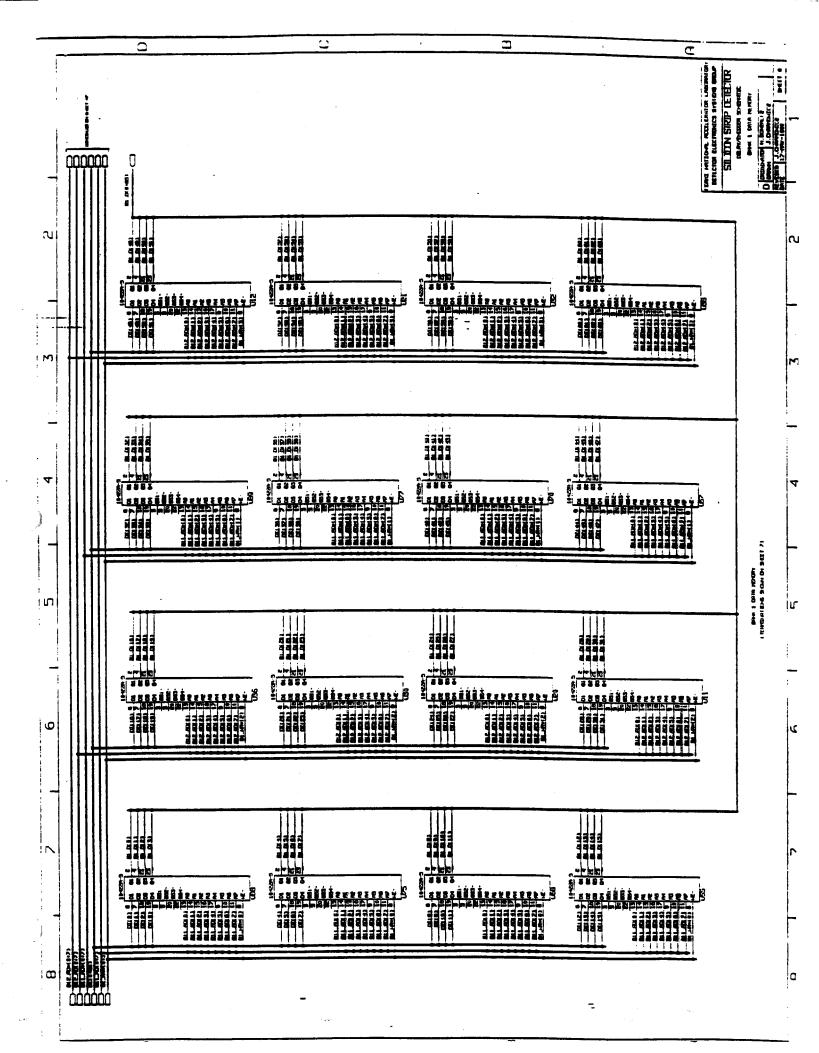


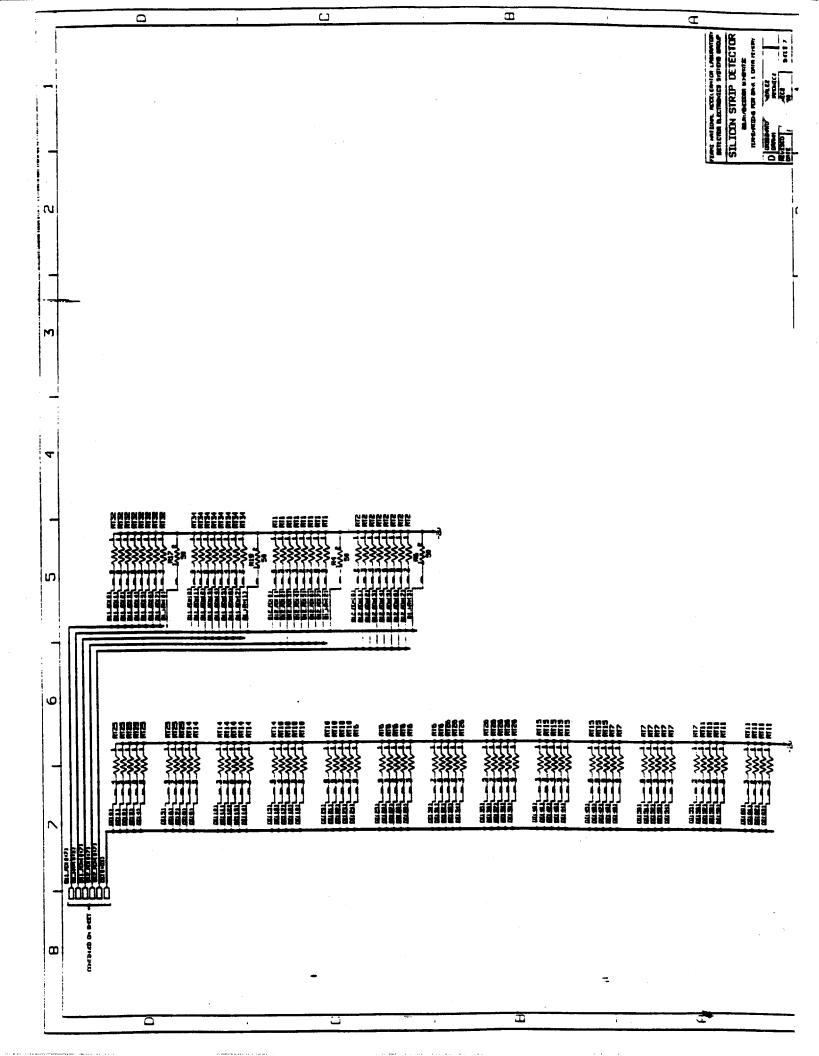


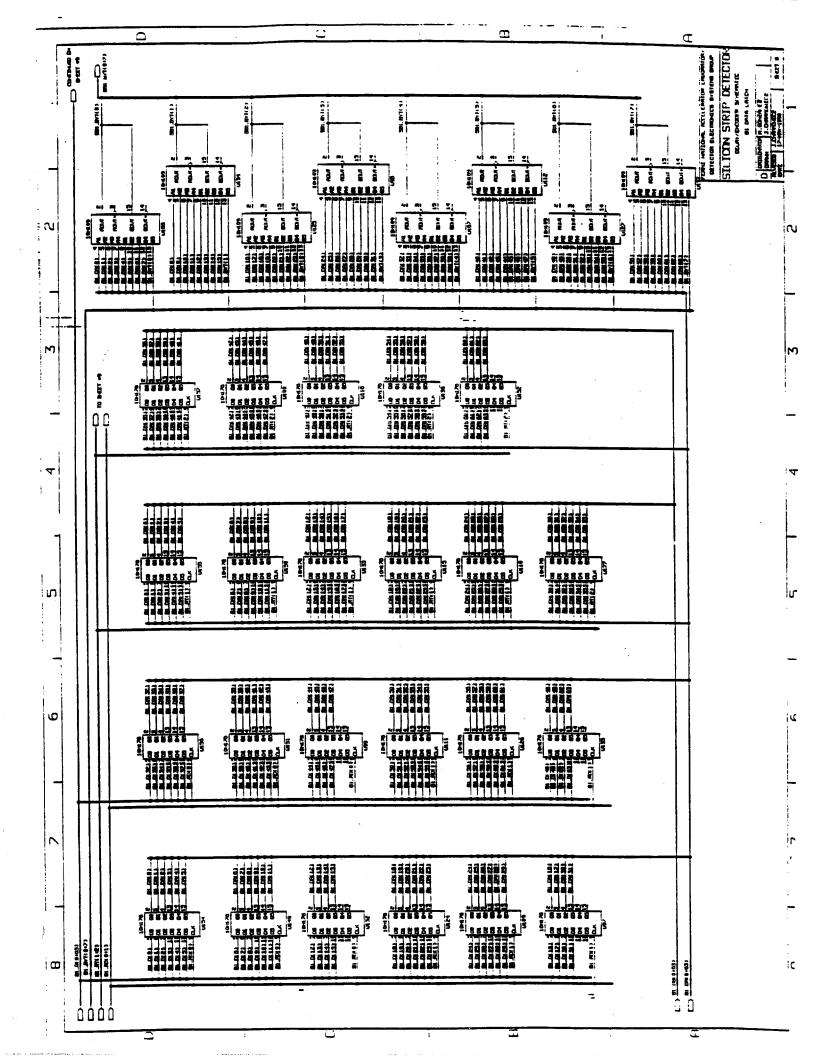


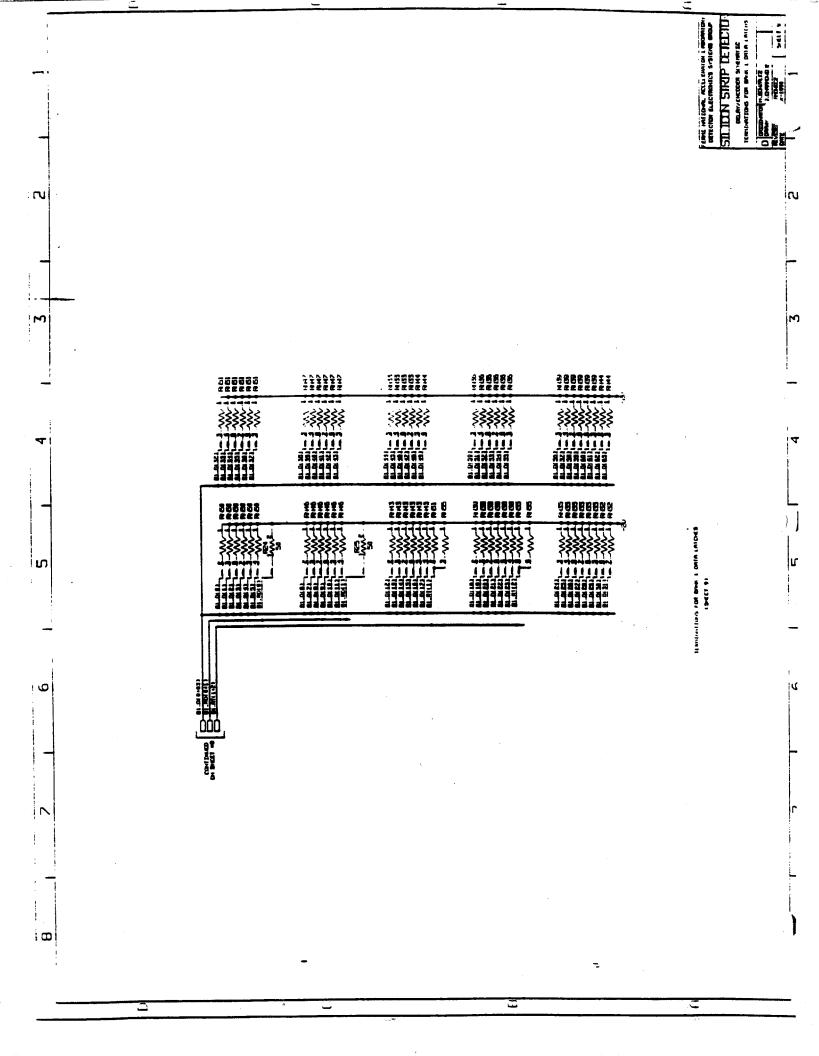


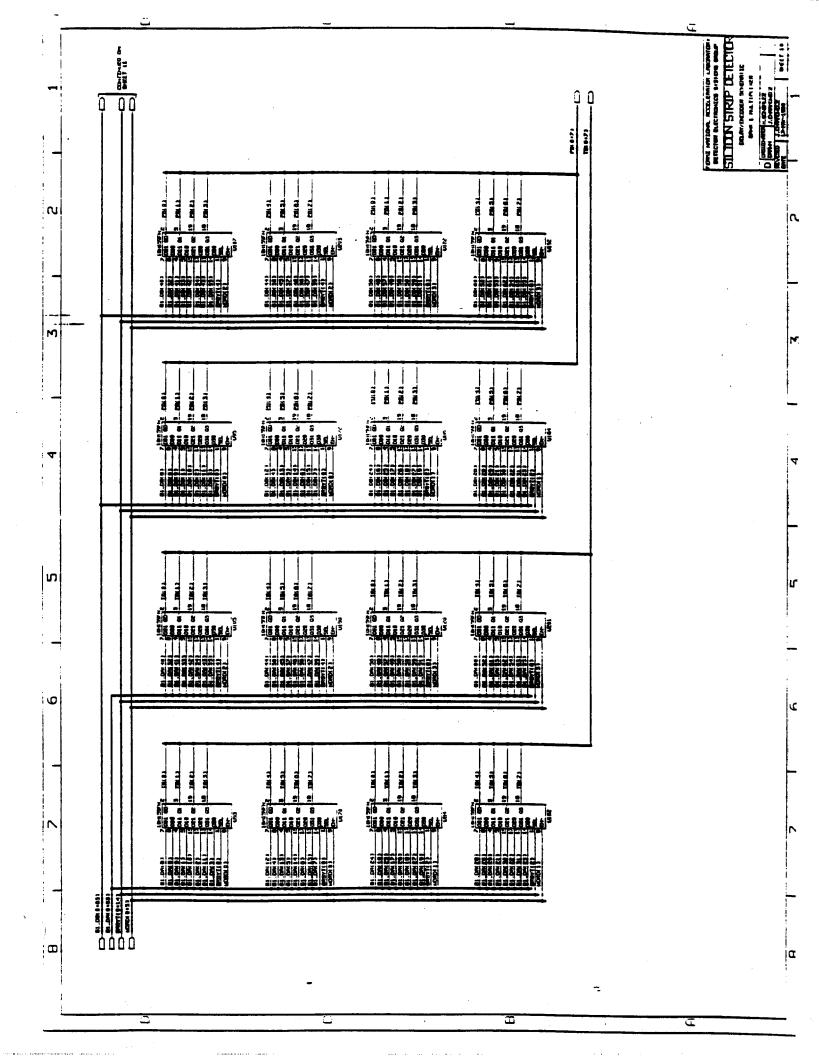


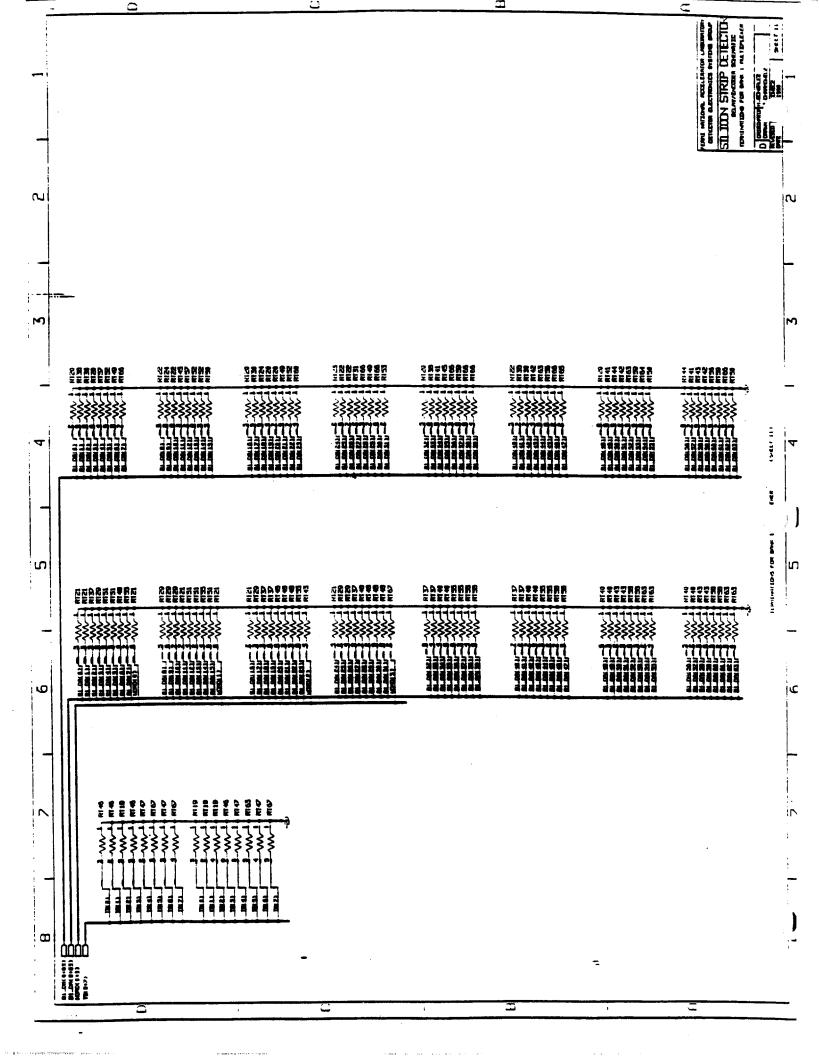


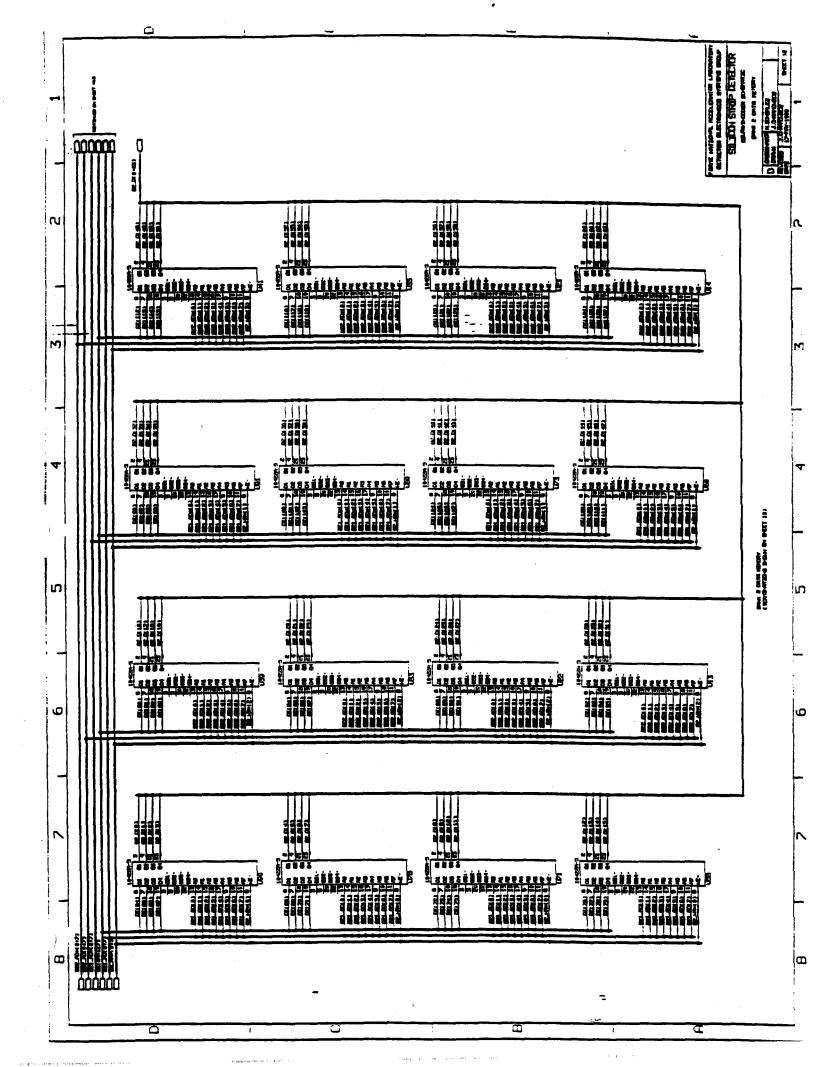


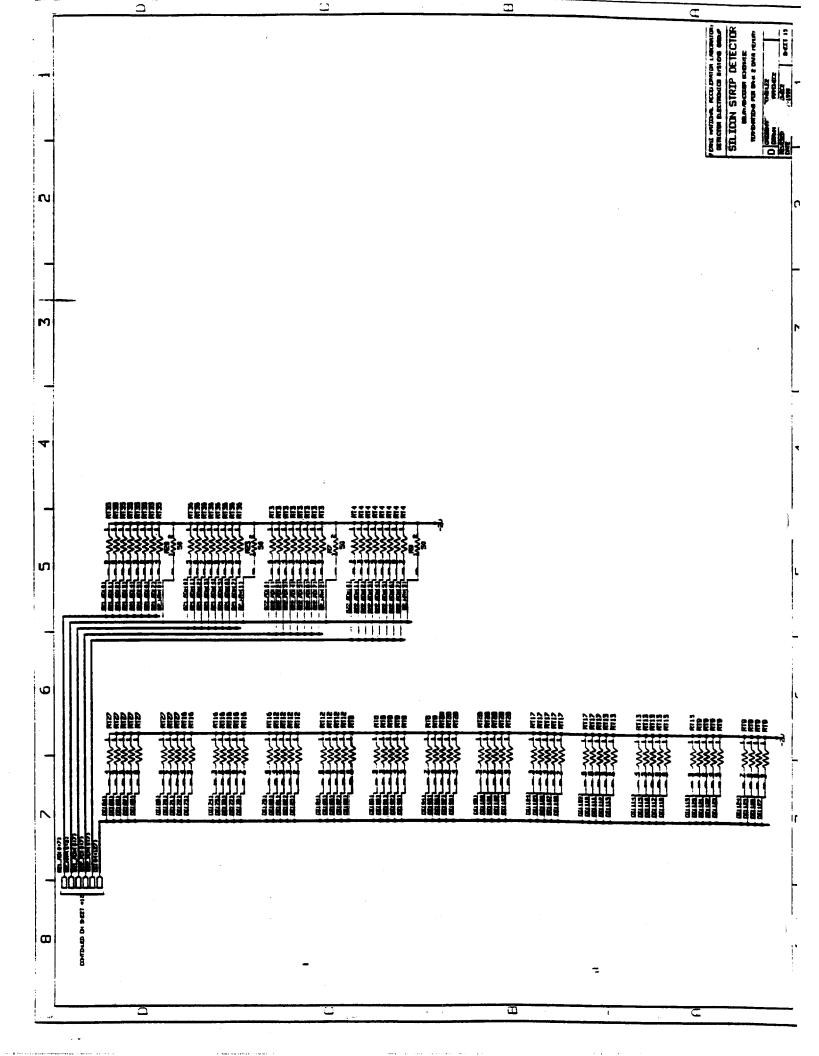


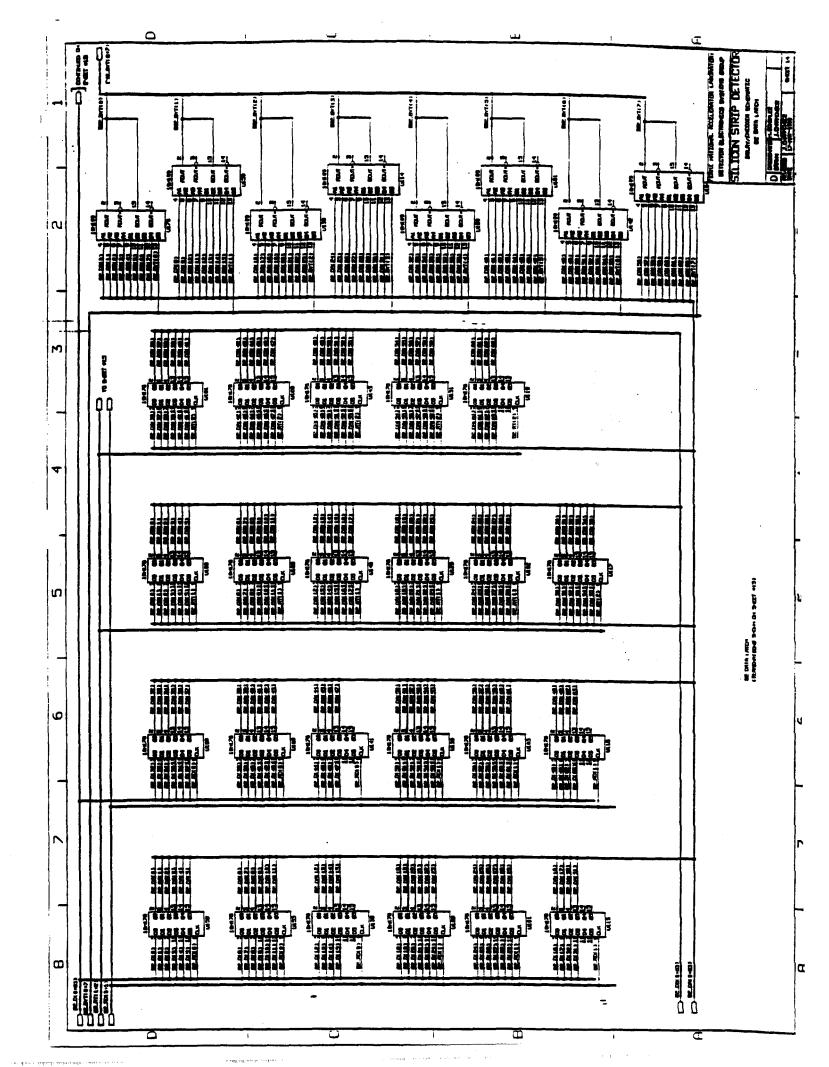




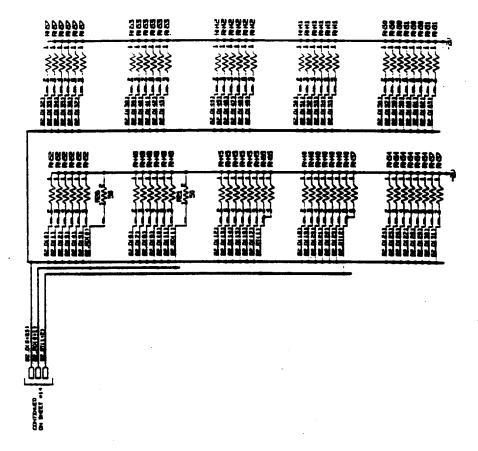












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